

ROBO-625

**ISA VIA Half-sized CPU card
with CPU, VGA/LCD, and
Ethernet**

Users Manual

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This manual is for the ROBO-625.

Part No. 21-6675

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Packing List

Before you begin installing your card, please make sure that the following materials have been shipped:

- 1 ROBO-625 all-in-one single board computer
- 1 startup manual
- CD-ROM or disks for utility, drivers, and manual (in PDF format)
- 1 power cable
- 1 PS/2 KB/M cable
- 1 COM port cable
- 1 Printer cable
- 1 VGA cable
- 1 FDD cable
- 1 EIDE cable

If any of these items are missing or damaged, contact your distributor or sales representative immediately.

Additional Information and Assistance

1. Visit the Portwell web site at **www.portwell.com** where you can find the latest information about the product.
2. Contact your distributor, sales representative, or Portwell's customer service center for technical support if you need additional assistance.

Please have the following information ready before you call:

- Product name and serial number
- Description of your peripheral attachments
- Description of your software (operating system, version, application software, etc.)
- A complete description of the problem
- The exact wording of any error messages

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CHAPTER
1

General Information

This chapter gives background information on the ROBO-625.

Sections include:

- Introduction
- Features
- Specifications
- Board layout and dimensions

Chapter 1 Introduction

1.1 Introduction

Portwell's new ROBO-625 is a new half-sized CPU card with onboard VIA low power CPU, Ezra800. The VIA Eden processor uses advanced 0.13 μ CMOS technology with 128KB L1 cache memory and 64KB L2 cache memory on die. This board with Eden400 CPU can operate without a fan at temperatures up to 60° C (140° F) and typically consumes under 14 Watts while supporting numerous peripherals. This SBC includes a 4X AGP controller, a PCI Ethernet interface, and 18-bit TTL interface. Its design is based on the half-sized CPU card and supports ISA bus expansion. Other on-board features include an FDD, LPT, 2 USBs, and 2 serial ports. The SSD solution supports CompactFlash. cards. With the optional adapter, ROBO-625 can support AC97 Audio.

This product uses a VIA VT8606 "TwisterT" chip with Integrated Savage4 2D/3D/Video Accelerator and supports 4X AGP VGA/LCD interface and up to 32 MB frame buffer using system memory. The ROBO-625 also supports one 10/100Mbps Ethernet connections with onboard RJ-45 connectors.

1.2 Features

- Embedded low power VIA Ezra 800MHz
- ISA bus half-sized CPU card
- Fanless operation at 60oC.
- One onboard RJ-45 connectors support 10/100Base-T Ethernet
- 4X AGP graphics for high performance applications
- FSB 133MHz (Ezra800)

1.3 Specifications

1.3.1 Standard SBC Functions

- **CPU:** Embedded VIA low power Ezra/Eden processor Ezra-800 (PCA-6772F-Q3A1, PCA-6772F-Q1A1)
- **System chipsets:** VIA VT8606 "TwisterT" + VT82C686B
- **BIOS:** Award 256 KB Flash memory
- **System memory:** One DIMM socket accepts 64 MB up to 512 MB SDRAM
- **2nd cache memory:** 64KB on the Ezra processor
- **Enhanced IDE interface:** One channel supports up to two EIDE devices. BIOS auto-detect, PIO Mode 3 or Mode 4, up to UDMA66/100 mode.
- **FDD interface:** Supports up to two FDDs
- **Serial ports:** Two serial RS-232 ports
- **Parallel port:** Parallel port supports SPP/EPP/ECP mode
- **Keyboard/mouse connector:** Supports standard PC/AT keyboard and a PS/2 mouse
- **Power management:** Supports power saving modes including Normal/Standby/Suspend modes. APM 1.2 compliant
- **Watchdog timer:** 62 level timer intervals
- **USB:** Two universal serial bus ports

1.3.2 VGA/LCD Interface

- **Chipset:** VIA VT8606 "TwisterT" chip with integrated Savage4 2D/3D/ Video Accelerator
- **Frame buffer:** Supports 8/16/32MB frame buffer with system memory
- **Interface:** 4X AGP VGA/LCD interface, Support for 9, 12, 15, 18 bit TFT
- **Display modes:**
 - CRT Modes: 1280 x 1024@16bpp (60Hz),
1024 x 768@16bpp (85Hz);
 - LCD/Simultaneous Modes:
800 x 600@18bpp (60Hz).
640 x 480@18bpp (60Hz))

1.3.3 Solid State disk

- Supports **CompactFlash Type I/II** disks

1.3.4 PCI bus Ethernet interface

- **Chipset:** REALTEK RTL8139C plus Ethernet controller
- **Ethernet interface:** IEEE 802.3U compatible 10/100Base-T interface.
Includes software drivers and boot ROM
- **Wake-on-LAN:** Supports wake-on-LAN function

1.3.5 Mechanical and Environmental

- **Dimensions (L x W):** 185 x 122 mm(7.28" x 4.80")
- **Power supply voltage:** +5 V, +12V ±5%
- **Power requirements:**
 - Max:**
4.5 A @ +5 V, 0.5 A @+12 V
 - Typical:**
3.3 A @ 5 V, (with 256 MB DRAM, Ezra 800 MHz CPU)
2.78 A @ 5 V, (with 256 MB DRAM, Eden 400 MHz CPU)
- **Operating temperature:** 0 ~ 60°C (32 ~ 140°F)
- **Operating humidity:** 0% ~ 90% Relative Humidity, Non condensing
- **Weight:** 0.27 kg (weight of total package)

1.4 Board layout: dimensions

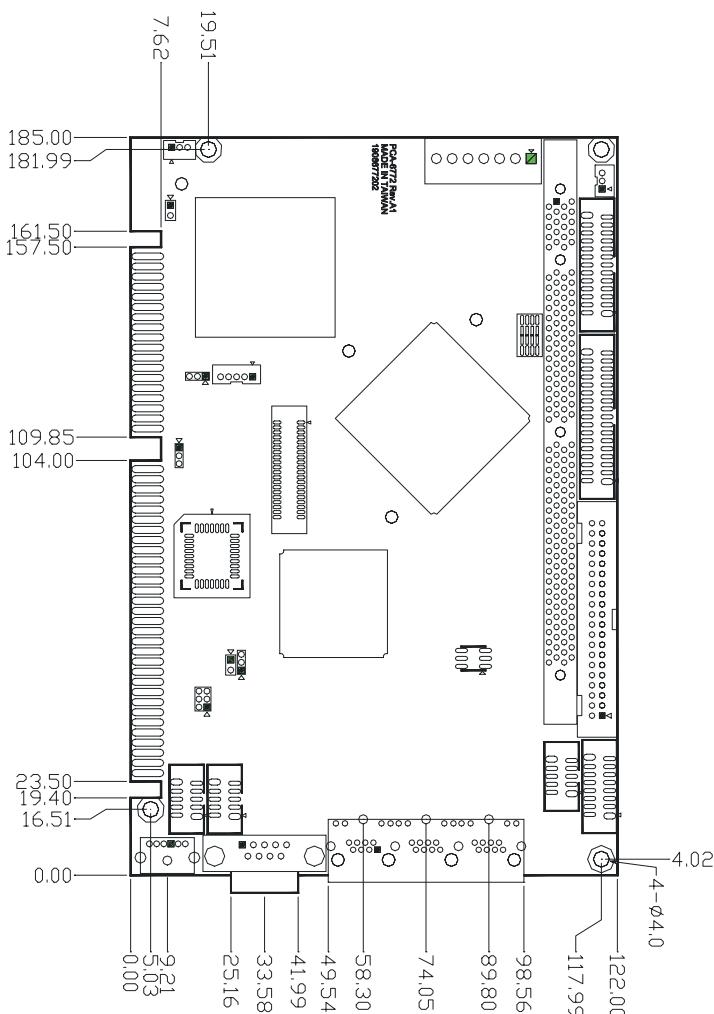


Figure 1.1: Board layout: dimensions (component side)

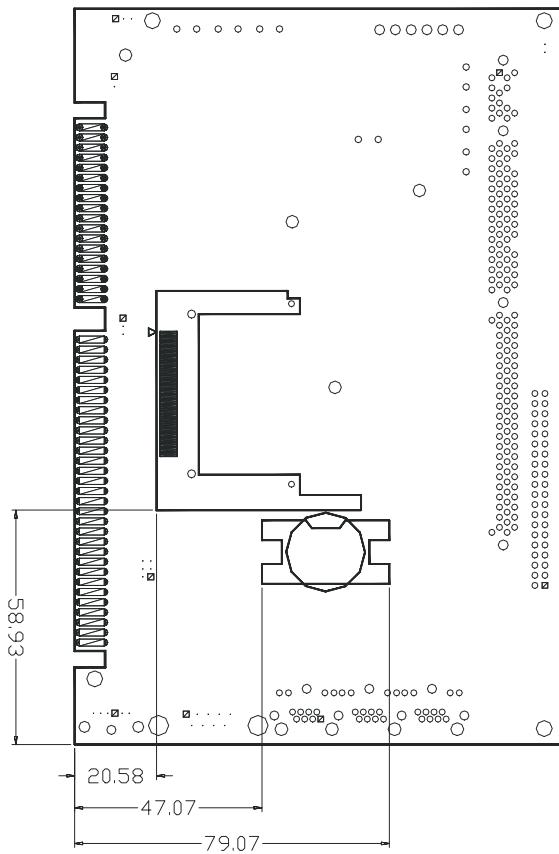


Figure 1.2: Board layout: dimensions (solder side)

CHAPTER
2

Installation

This chapter explains the setup procedures of ROBO-625 hardware, including instructions on setting jumpers and connecting peripherals, switches and indicators. Be sure to read all safety precautions before you begin the installation procedure.

Chapter 2 Installation

2.1 Jumpers

The ROBO-625 has a number of jumpers that allow you to configure your system to suit your application. The table below lists the functions of the various jumpers.

Table 2.1: Jumpers

| Label | Function |
|-------|-------------------------|
| JP1 | CMOS clear |
| JP2 | LAN Vcc select |
| JP3 | Watch-Dog output select |
| S1 | Panel type select |

2.2 Connectors

On-board connectors link the ROBO-625 to external devices such as hard disk drives, a keyboard, or floppy drives. The table below lists the function of each of the board's connectors.

Table 2.2: Connectors

| Label | Function |
|-------|-----------------------------------|
| CN1 | ATX power control connector |
| CN2 | Printer port connector |
| CN3 | FDD connector |
| CN4 | Primary IDE connector |
| CN5 | CRT display connector |
| CN6 | USB connectors |
| CN7 | LAN1, LAN2, LAN3 RJ45 connector |
| CN8 | Main power connector |
| CN9 | Power and HDD LED connector |
| CN12 | Flat panel display connector |
| CN13 | COM port connector |
| CN14 | Panel back-light power connector |
| CN15 | ATX soft power switch connector |
| CN16 | COM port connector |
| CN17 | Panel back-light VR connector |
| CN19 | Reset switch connector |
| CN20 | Keyboard and PS/2 mouse connector |
| Fan1 | CPU fan power connector |

2.3 Locating jumpers

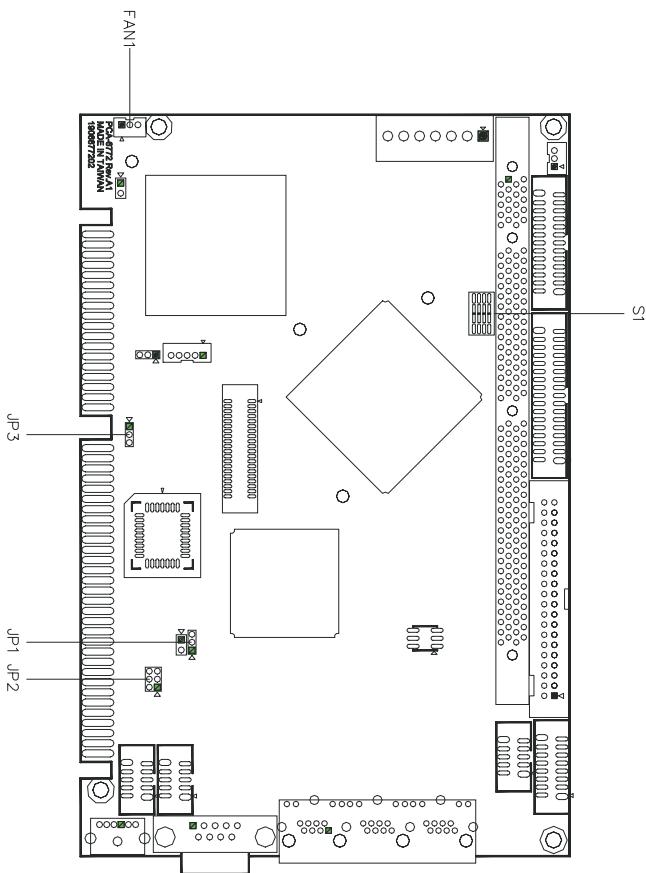


Figure 2.1: Jumper locations

2.4 Locating Connectors

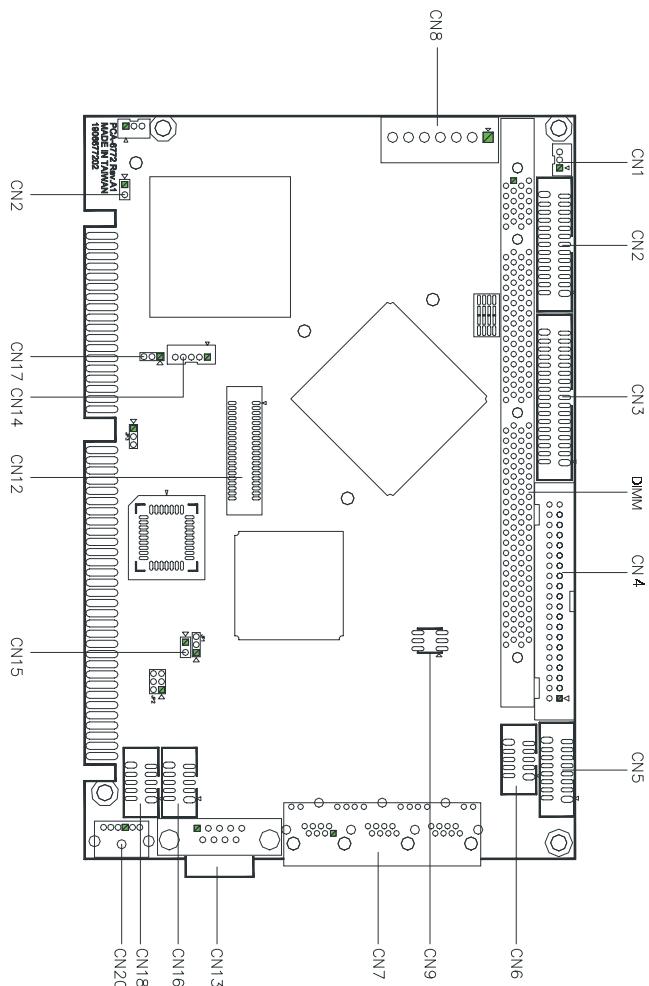
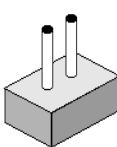


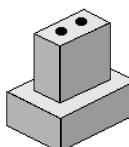
Figure 2.2: Connectors (component side)

2.5 Setting Jumpers

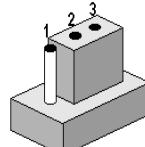
You may configure your card to match the needs of your application by setting jumpers. A jumper is a metal bridge used to close an electric circuit. It consists of two metal pins and a small metal clip (often protected by a plastic cover) that slides over the pins to connect them. To “close” a jumper, you connect the pins with the clip. To “open” a jumper, you remove the clip. Sometimes a jumper will have three pins, labeled 1, 2 and 3. In this case you would connect either pins 1 and 2, or 2 and 3.



open

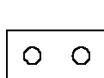


closed



closed 2-3

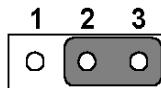
The jumper settings are schematically depicted in this manual as follows::



open



closed



closed 2-3

A pair of needle-nose pliers may be helpful when working with jumpers.

If you have any doubts about the best hardware configuration for your application, contact your local distributor or sales representative before you make any changes.

Generally, you simply need a standard cable to make most connections.

2.6 Clear CMOS (JP1)

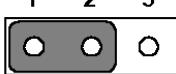
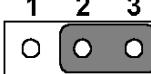
Warning! To avoid damaging the computer, always turn off the power supply before setting “Clear CMOS.” Before turning on the power supply, set the jumper back to “3.0 V Battery On.”

This jumper is used to erase CMOS data and reset system BIOS information.

The procedure for clearing CMOS is:

1. Turn off the system.
2. Short pin 2 and pin 3.
3. Return jumper to pins 1 and 2.
4. Turn on the system. The BIOS is now reset to its default setting

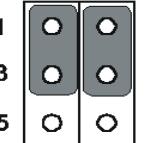
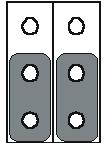
Table 2.3: CMOS clear (JP1)

| *3.0 V normal | clear CMOS |
|---|---|
|  |  |

* default setting

2.7 LAN Vcc select (JP2)

Table 2.4: LAN Vcc select (JP2)

| Normal power* | WOL power |
|---|---|
|  |  |

* default setting

Note: ROBO-625 supports Wake-on-LAN. For Wake-on LAN, JP2 has to be set to the WOL power position

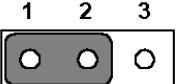
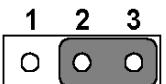
2.8 Watchdog timer configuration

An on-board watchdog timer reduces the chance of disruptions which EMP (electro-magnetic pulse) interference can cause. This is an invaluable protective device for standalone or unmanned applications. Setup involves one jumper and running the control software (refer to Appendix A).

2.8.1 Watchdog timer action (JP3)

When the watchdog timer activates (CPU processing has come to a halt), it can reset the system or generate an interrupt on IRQ11. This can be set via setting JP3 as shown below:

Table 2.5: Watchdog timer action (JP3)

| *System reset | IRQ 11 |
|---|---|
|  |  |

* default setting

2.9 Installing DIMMs

The procedure for installing DIMMs is described below. Please follow these steps carefully. The number of pins are different on either side of the breaks, so the module can only fit in one way. DIMM modules have different pin contacts on each side, and therefore have a higher pin density.

1. Make sure that the two handles of the DIMM socket are in the “open” position. i.e. The handles remain leaning outward.
2. Slowly slide the DIMM module along the plastic guides on both ends of the socket.
3. Press the DIMM module right down into the socket, until you hear a click. This is when the two handles have automatically locked the memory module into the correct position of the socket.

To **remove** the memory module, just push both handles outward, and the module will be ejected from the socket.

2.10 ATX power control connector (CN1,CN15)

2.10.1 ATX feature connector (CN1) and soft power switch connector (CN15)

The ROBO-625 can support an advanced soft power switch function, if an ATX power supply is used. To enable the soft power switch function:

1. Get the specially designed ATX-to-SBC power cable
2. Connect the 3-pin plug of the cable to CN1 (ATX feature connector).
3. Connect the power on/off button to CN15. (A momentary type of button should be used.)

Important *Make sure that the ATX power supply can take at least a 10 mA load on the 5 V standby lead (5VSB). If not, you may have difficulty powering on your system.*

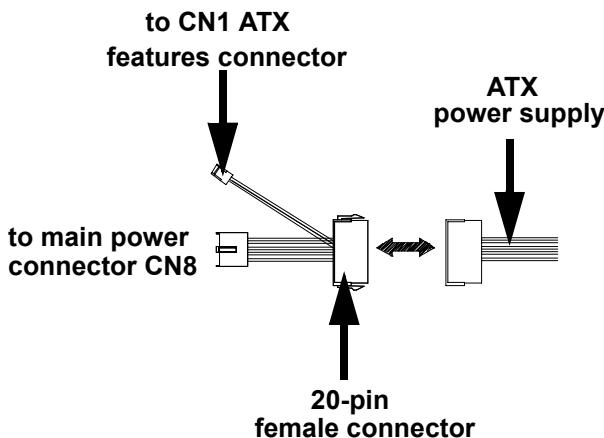


Figure 2.3: Wiring for ATX soft power switch function

2.11 Printer port connector (CN2)

Normally, the parallel port is used to connect the card to a printer. The ROBO-625 includes a multi-mode (ECP/EPP/SPP) parallel port accessed via CN2 and a 26-pin flat-cable connector. You will need an adapter cable if you use a traditional DB-25 connector. The adapter cable has a 26-pin connector on one end, and a DB-25 connector on the other.

The parallel port is designated as LPT1, and can be disabled or changed to LPT2 or LPT3 in the system BIOS setup.

The parallel port interrupt channel is designated to be IRQ7.

You can select ECP/EPP DMA channel via BIOS setup.

2.12 Floppy drive connector (CN3)

You can attach up to two floppy drives to the ROBO-625's on-board controller. You can use any combination of 5.25" (360 KB and 1.2 MB) and/or 3.5" (720 KB, 1.44 MB, and 2.88 MB) drives.

A 34-pin daisy-chain drive connector cable is required for a dual-drive system. On one end of the cable is a 34-pin flat-cable connector. On the other end are two sets of floppy disk drive connectors. Each set consists of a 34-pin flat-cable connector (usually used for 3.5" drives) and a printed-circuit board connector (usually used for 5.25" drives).

2.12.1 Connecting the floppy drive

1. Plug the 34-pin flat-cable connector into CN3. Make sure that the red wire corresponds to pin one on the connector.
2. Attach the appropriate connector on the other end of the cable to the floppy drive(s). You can use only one connector in the set. The set on the end (after the twist in the cable) connects to the A: drive. The set in the middle connects to the B: drive.
3. If you are connecting a 5.25" floppy drive, line up the slot in the printed circuit board with the blocked-off part of the cable connector.

If you are connecting a 3.5" floppy drive, you may have trouble determining which pin is number one. Look for a number printed on the circuit board indicating pin number one. In addition, the connector on the floppy drive may have a slot. When the slot is up, pin number one should be on the right. Check the documentation that came with the drive for more information.

If you desire, connect the B: drive to the connectors in the middle of the cable as described above.

In case you need to make your own cable, you can find the pin assignments for the board's connector in Appendix C.

2.13 Primary IDE connector(CN4)

The ROBO-625 provides an IDE channel to which you can attach up to two Enhanced Integrated Device Electronics hard disk drives or CDROM to the ROBO-625's internal controller. The ROBO-625's IDE controller uses a PCI interface. This advanced IDE controller supports faster data transfer, PIO Mode 3 or Mode 4, UDMA 33/66/100 mode.

2.13.1 Connecting the hard drive

Connecting drives is done in a daisy-chain fashion. It requires one of two cables (not included in this package), depending on the drive size. 1.8" and 2.5" drives need a 1 x 44-pin to 2 x 44-pin flat-cable connector. 3.5" drives use a 1 x 44-pin to 2 x 40-pin connector.

Wire number 1 on the cable is red or blue, and the other wires are gray.

1. Connect one end of the cable to CN4. Make sure that the red (or blue) wire corresponds to pin 1 on the connector, which is labeled on the board (on the right side).
2. Plug the other end of the cable into the Enhanced IDE hard drive, with pin 1 on the cable corresponding to pin 1 on the hard drive. (See your hard drive's documentation for the location of the connector.)

If desired, connect a second drive as described above.

Unlike floppy drives, IDE hard drives can connect to either end of the cable. If you install two drives, you will need to set one as the master and one as the slave by using jumpers on the drives. If you install only one drive, set it as the master.

2.14 VGA/LCD interface connections

The ROBO-625's display interface can drive conventional CRT displays and is capable of driving a wide range of flat panel displays as well, including passive LCD and active LCD displays. The board has two display connectors: one for standard CRT VGA monitors, and one for flat panel displays.

2.14.1 CRT display connector (CN5)

CN5 is a 16-pin, dual-inline header used for conventional CRT displays. A simple one-to-one adapter can be used to match CN5 to a standard 15-pin D-SUB connector commonly used for VGA.

Pin assignments for CRT display connector CN5 are detailed in Appendix C.

2.14.2 Flat panel display connector (CN12)

CN12 consists of a 40-pin connector which can support an 18-bit LCD panel. It is Hirose's product no. DF13A-40DP-1.25 V

The ROBO-625 provides a bias control signal on CN12 that can be used to control the LCD bias voltage. It is recommended that the LCD bias voltage not be applied to the panel until the logic supply voltage (+5 V or +3.3 V) and panel video signals are stable. Under normal operation, the control signal (ENAVEE) is active high. When the ROBO-625's power is applied, the control signal is low until just after the relevant flat panel signals are present. CN12 can connect up to 18 bit TFT LCD.

2.14.3 Panel type selection (S1)

S1 is an 8 segment DIP switch for DSTN/TFT panel type and resolution functions.

Table 2.6: S1 Panel Type select

| SW 1-1 | SW 1-2 | SW 1-3 | SW 1-4 | Panel Type & Resolution | | |
|-------------------|-------------------|-------------------|-------------------|------------------------------------|------------|--------------------|
| ON | ON | ON | ON | TFT | 640x480** | 18bit (H. V. Freq) |
| ON | ON | ON | OFF | TFT | 648x480 | 18bit (Synthetic) |
| ON | ON | OFF | ON | TFT | 648x480** | N/A |
| ON | ON | OFF | OFF | TFT | 648x480** | LVDS |
| ON | OFF | ON | ON | DSTN | 648x480** | 18bit |
| ON | OFF | ON | OFF | TFT | 800x600** | 18bit (H. V. Freq) |
| ON | OFF | OFF | ON | TFT | 800x600 | 18bit (Synthetic) |
| ON | OFF | OFF | OFF | TFT | 800x600** | LVDS |
| OFF | ON | ON | ON | TFT | 800x600** | N/A |
| OFF | ON | ON | OFF | DSTN | 800x600** | 18bit |
| OFF | ON | OFF | ON | TFT | 1024x768** | 36bit (H. V. Freq) |
| OFF | ON | OFF | OFF | TFT | 1024x768** | 36bit (Synthetic) |
| OFF | OFF | ON | ON | TFT | 1024x768** | LVDS |
| OFF | OFF | ON | OFF | TFT | 1024x768** | N/A |
| OFF | OFF | OFF | ON | DSTN | 1024x768** | 18bit |
| OFF | OFF | OFF | OFF | DSTN | 1024x768** | 24bit |

* Default setting

** will support in the future

2.15 USB connectors (CN6)

The ROBO-625 board provides up to two USB (Universal Serial Bus) ports. This gives complete Plug and Play, and hot attach/detach for up to 127 external devices. The USB interfaces comply with USB specification Rev. 1.1, and are fuse protected.

The USB interface is accessed through the 5 x 2-pin flat-cable connector, CN6 (USB1, 2). You will need an adapter cable if you use a standard

USB connector. The adapter cable has a 5 x 2-pin connector on one end and a USB connector on the other.

The USB interfaces can be disabled in the system BIOS setup.

2.16 Ethernet configuration

The ROBO-625 is equipped with a high performance 32-bit PCI-bus Ethernet interface which is fully compliant with IEEE 802.3U 10/100Mbps CSMA/CD standards. It is supported by all major network operating systems.

The ROBO-625 supports up to 3 10/100Mbps Ethernet connections with onboard RJ-45 connectors(CN7) and is effective for use as a firewall, VPN, or gateway device.

The medium type can be configured via the RSET8139.EXE program included on the utility disk. (See Chapter 3 for detailed information.)

2.16.1 100Base-T connector (CN7)

10/100Base-T connects to the ROBO-625 via an adapter cable to an 8-pin polarized header (CN7).

2.16.2 Network boot

The Network Boot feature can be utilized by incorporating the Boot ROM image files for the appropriate network operating system. The Boot ROM BIOS files are included in the system BIOS, which is on the utility CD disc.

2.17 Power connectors (CN8, FAN1)

2.17.1 Main power connector, +5 V, +12 V (CN8)

Supplies main power to the PCA-6772 (+5 V), and to devices that require +12 V.

2.17.2 CPU Fan power supply connector (FAN1)

Provides power supply to CPU cooling fan. Only present when +5 V and +12 V power is supplied to the board.

2.18 Power & HDD LED, Reset Button Connector (CN9, CN19)

Next, you may want to install external switches to monitor and control the ROBO-625. These features are optional: install them only if you need

them. The front panel connector (CN9) is an 6-pin male, dual in-line header. It provides connections for a speaker, hard disk access indicator, watchdog output, and an input switch for resetting the card.

2.18.1 Power & HDD LED (CN9)

The HDD LED indicator for hard disk access is an active low signal (24 mA sink rate). Power supply activity LED indicator.

2.18.2 Reset switch (CN19)

If you install a reset switch, it should be an open single pole switch. Momentarily pressing the switch will activate a reset. The switch should be rated for 10 mA, 5 V.

2.19 COM port connector (CN13,CN16)

The ROBO-625 provides two serial ports (COM1: RS-232 and COM2: RS232) in one COM port connector. It provides connections for serial devices (a mouse, etc.) or a communication network. You can find the pin assignments for the COM port connector in Appendix C.

2.20 Keyboard and PS/2 mouse connector (CN20)

The ROBO-625 board provides a keyboard connector that supports both a keyboard and a PS/2 style mouse. In most cases, especially in embedded applications, a keyboard is not used. If the keyboard is not present, the standard PC/AT BIOS will report an error or fail during power-on self-test (POST) after a reset. The ROBO-625's BIOS standard setup menu allows you to select "All, But Keyboard" under the "Halt On" selection. This allows no-keyboard operation in embedded system applications, without the system halting under POST.

2.21 Audio AC97 interface (CN18)

2.21.1 Audio connector (CN18)

The Audio AC97 link is a 10 pin connector; the ROBO-625 can support AC97 Audio with the addition of optional adapter.

CHAPTER
3

Software Configuration

This chapter details the software configuration information. It shows you how to configure the card to match your application requirements. The AWARD System BIOS is covered in Chapter 4.

Sections include:

- Introduction
- Connections for standard LCDs
- Ethernet interface configuration.

Chapter 3 Software Configuration

3.1 Introduction

The ROBO-625 system BIOS and custom drivers are located in a 256 Kbyte, Flash ROM device, designated U18. A single Flash chip holds the system BIOS, VGA BIOS and network Boot ROM image. The display can be configured via CMOS settings. This method minimizes the number of chips and difficulty of configuration. To set different types of LCD panels, please choose “panel type” from the “integrated peripherals” menu in CMOS setup.

3.2 Connections to Two Standard LCDs

The following tables illustrate typical LCD connection pinouts for the ROBO-625.

3.2.1 Connections to Toshiba LTM10C209A (640 x 480 TFT color LCD)

Table 3.1: Connections to Toshiba LTM10C209A

| LTM10C209A | | ROBO-625 CN12 | |
|------------|------|---------------|--------|
| Pin | Name | Pin | Name |
| 1 | GND | 3 | GND |
| 2 | CLK | 35 | SHFCLK |
| 3 | GND | 34 | GND |
| 4 | R0 | 27 | P18 |
| 5 | R1 | 28 | P19 |
| 6 | R2 | 29 | P20 |
| 7 | GND | 33 | GND |
| 8 | R3 | 30 | P21 |
| 9 | R4 | 31 | P22 |
| 10 | R5 | 32 | P23 |
| 11 | GND | 34 | GND |
| 12 | G0 | 19 | P10 |
| 13 | G1 | 20 | P11 |
| 14 | G2 | 21 | P12 |
| 15 | GND | 8 | GND |
| 16 | G3 | 22 | P13 |
| 17 | G4 | 23 | P14 |
| 18 | G5 | 24 | P15 |
| 19 | GND | 8 | GND |
| 20 | ENAB | 37 | M/DE |
| 21 | GND | 4 | GND |
| 22 | B0 | 11 | P2 |
| 23 | B1 | 12 | P3 |
| 24 | B2 | 13 | P4 |
| 25 | GND | 4 | GND |
| 26 | B3 | 14 | P5 |
| 27 | B4 | 15 | P6 |

Table 3.1: Connections to Toshiba LTM10C209A

| | | | |
|----|-----|----|------|
| 28 | B5 | 16 | P7 |
| 29 | GND | 3 | GND |
| 30 | VDD | 1 | +5 V |
| 31 | VDD | 2 | +5 V |

3.2.2 Connections to Toshiba LTM12C275A (800 x 600 TFT color LCD)

Table 3.2: Connections to Toshiba LTM12C275A

| LTM12C275A | | ROBO-625 CN12 | |
|------------|------|---------------|--------|
| Pin | Name | Pin | Name |
| 1 | GND | 3 | GND |
| 2 | NCLK | 35 | SHFCLK |
| 3 | NC | - | NC |
| 4 | NC | - | NC |
| 5 | GND | 4 | GND |
| 6 | R0 | 27 | P18 |
| 7 | R1 | 28 | P19 |
| 8 | R2 | 29 | P20 |
| 9 | R3 | 30 | P21 |
| 10 | R4 | 31 | P22 |
| 11 | R5 | 32 | P23 |
| 12 | GND | 8 | GND |
| 13 | G0 | 19 | P10 |
| 14 | G1 | 20 | P11 |
| 15 | G2 | 21 | P12 |
| 16 | G3 | 22 | P13 |
| 17 | G4 | 23 | P14 |
| 18 | G5 | 24 | P15 |
| 19 | GND | 33 | GND |
| 20 | B0 | 11 | P2 |
| 21 | B1 | 12 | P3 |
| 22 | B2 | 13 | P4 |
| 23 | B3 | 14 | P5 |
| 24 | B4 | 15 | P6 |
| 25 | B5 | 16 | P7 |
| 26 | ENAB | 37 | M/DE |
| 27 | GND | 34 | GND |
| 28 | VCC | 5 | +5 V |
| 29 | VCC | 6 | +5 V |
| 30 | GND | 39 | GND |

3.3 Ethernet software configuration

The ROBO-625's on-board Ethernet interface supports all major network operating systems. To configure the medium type, to view the current configuration, or to run diagnostics, do the following:

1. Power the ROBO-625 on. Make sure that the RSET8139.EXE file is located in the working drive.
2. At the prompt, type RSET8139.EXE and press <Enter>. The Ethernet configuration program will then be displayed.
3. This simple screen shows all the available options for the Ethernet interface. Just highlight the option you wish to change by using the Up and Down keys. To change a selected item, press <Enter>, and a screen will appear with the available options. Highlight your option and press <Enter>. Each highlighted option has a helpful message guide displayed at the bottom of the screen for additional information.
4. After you have made your selections and are sure this is the configuration you want, press ESC. A prompt will appear asking if you want to save the configuration. Press Y if you want to save.

The Ethernet Setup Menu also offers three very useful diagnostic functions. These are:

1. Run EEPROM Test.
2. Run Diagnostics on Board.
3. Run Diagnostics on Network.

Each option has its own display screen that shows the format and result of any diagnostic tests undertaken.

Note

For Ethernet installation, please see Chapter 7

CHAPTER
4

Award BIOS Setup

This chapter describes how to set BIOS configuration data.

Chapter 4 Award BIOS Setup

4.1 System test and initialization

These routines test and initialize board hardware. If the routines encounter an error during the tests, you will either hear a few short beeps or see an error message on the screen. There are two kinds of errors: fatal and non-fatal. The system can usually continue the boot up sequence with non-fatal errors. Non-fatal error messages usually appear on the screen along with the following instructions:

press <F1> to RESUME

Write down the message and press the F1 key to continue the bootup sequence.

4.1.1 System configuration verification

These routines check the current system configuration against the values stored in the board's CMOS memory. If they do not match, the program outputs an error message. You will then need to run the BIOS setup program to set the configuration information in memory.

There are three situations in which you will need to change the CMOS settings:

1. You are starting your system for the first time
2. You have changed the hardware attached to your system
3. The CMOS memory has lost power and the configuration information has been erased.

The ROBO-625 Series' CMOS memory has an integral lithium battery backup. The battery backup should last ten years in normal service, but when it finally runs down, you will need to replace the complete unit.

4.2 Award BIOS setup

Award's BIOS ROM has a built-in Setup program that allows users to modify the basic system configuration. This type of information is stored in battery-backed CMOS RAM so that it retains the Setup information when the power is turned off.

4.2.1 Entering setup

Power on the computer and press immediately. This will allow you to enter Setup.

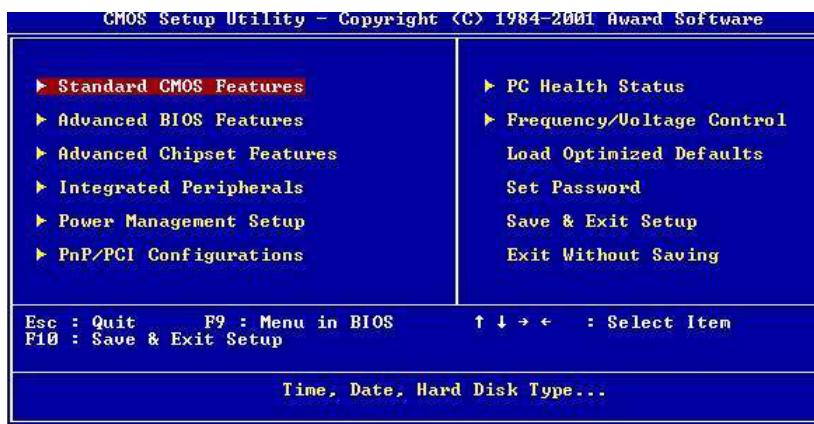


Figure 4.1: BIOS setup program initial screen

4.2.2 Standard CMOS Features setup

When you choose the Standard CMOS Features option from the Initial Setup Screen menu, the screen shown below is displayed. This standard Setup Menu allows users to configure system components such as date, time, hard disk drive, floppy drive and display. Once a field is highlighted, on-line help information is displayed in the left bottom of the Menu screen.

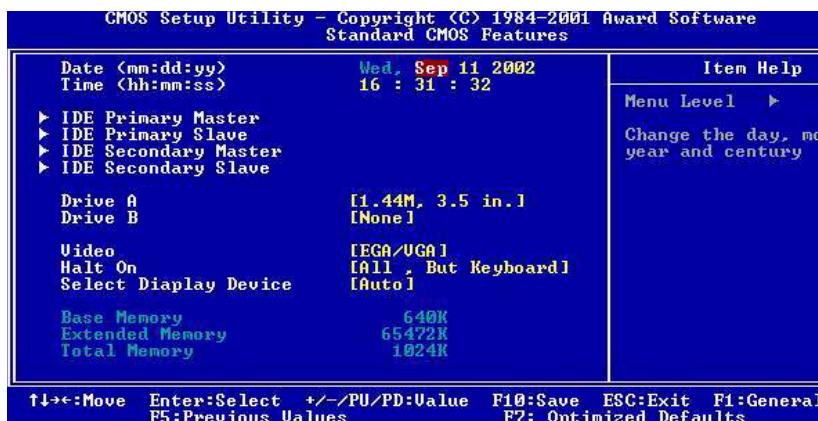


Figure 4.2: CMOS Features setup

4.2.3 Advanced BIOS Features setup

By choosing the Advanced BIOS Features Setup option from the Initial Setup Screen menu, the screen below is displayed. This sample screen contains the manufacturer's default values for the ROBO-625 Series.



Figure 4.3: Advanced BIOS Features setup

4.2.4 Advanced Chipset Features setup

By choosing the Advanced Chipset Features option from the Initial Setup Screen menu, the screen below is displayed. This sample screen contains the manufacturer's default values for the ROBO-625 Series.



Figure 4.4: Advanced Chipset Features setup

4.2.5 Integrated Peripherals

Choosing the Integrated Peripherals option from the Initial Setup Screen menu should produce the screen below. Here we see the manufacturer's default values for the ROBO-625 Series.



Figure 4.5: Integrated Peripherals

4.2.6 Power Management Setup

By choosing the Power Management Setup option from the Initial Setup Screen menu, the screen below is displayed. This sample screen contains the manufacturer's default values for the ROBO-625 Series.

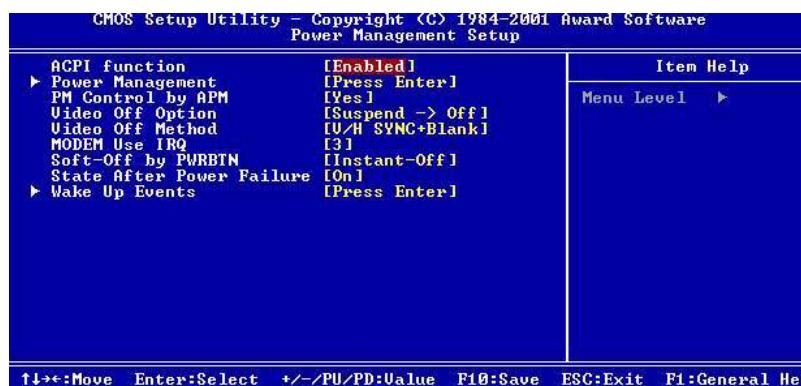


Figure 4.6: Power Management Setup

4.2.7 PnP/PCI Configurations

By choosing the PnP/PCI Configurations option from the Initial Setup Screen menu, the screen below is displayed. This sample screen contains the manufacturer's default values for the ROBO-625 Series.

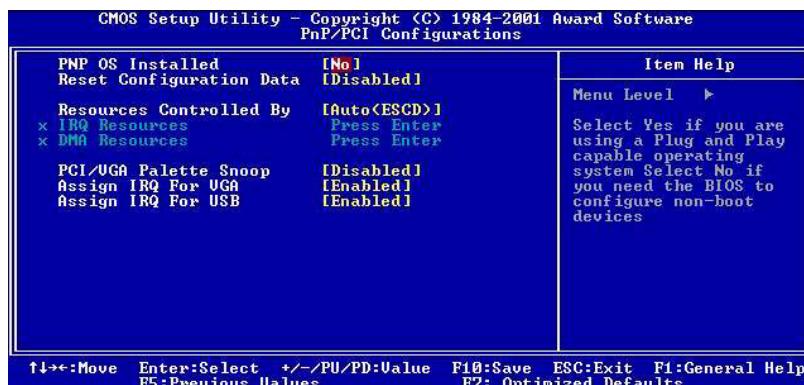


Figure 4.7: PnP/PCI Configurations

4.2.8 PC Health Status

The PC Health Status option displays information such as CPU and motherboard temperatures, fan speeds, and core voltage.



Figure 4.8: PC Health Status

4.2.9 Frequency/Voltage Control

By choosing the Frequency/Voltage Control option from the Initial Setup Screen menu, the screen below is displayed. This sample screen contains the manufacturer's default values for the ROBO-625

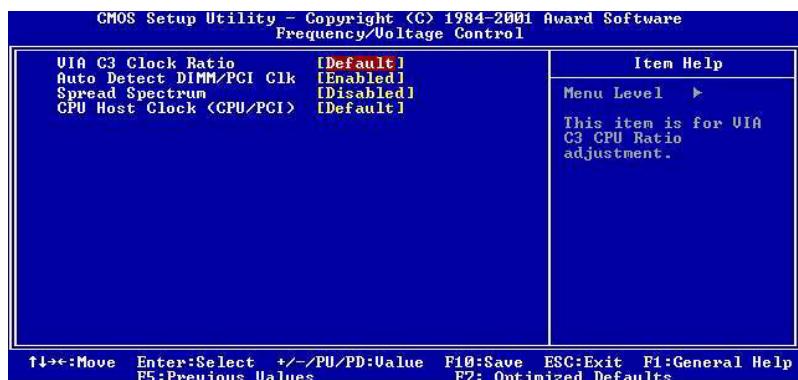


Figure 4.9: Frequency/Voltage Control

Caution

Incorrect settings in Frequency/Voltage Control may damage the system CPU, video adapter, or other hardware.

4.2.10 Load Optimized Defaults

Load Optimized Defaults loads the default system values directly from ROM. If the stored record created by the Setup program should ever become corrupted (and therefore unusable), these defaults will load automatically when you turn the ROBO-625 Series system on.

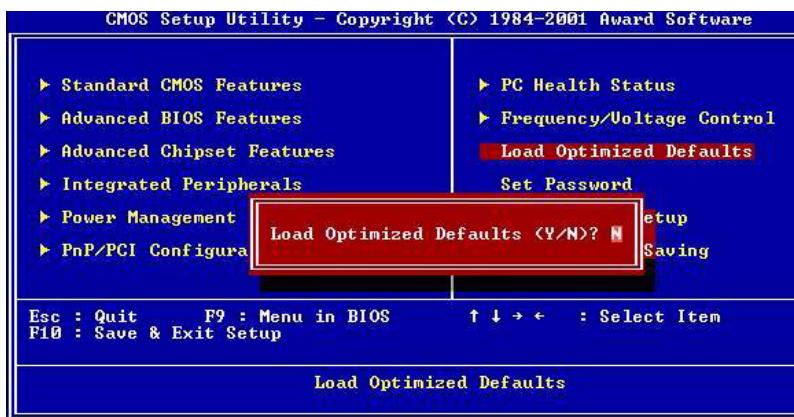


Figure 4.10: Load BIOS defaults screen

4.2.11 Set Password

Note To enable this feature, you should first go to the Advanced BIOS Features menu, choose the Security Option, and select either Setup or System, depending on which aspect you want password protected. Setup requires a password only to enter Setup. System requires the password either to enter Setup or to boot the system.

A password may be at most 8 characters long.

To Establish Password

1. Choose the Set Password option from the CMOS Setup Utility main menu and press <Enter>.
2. When you see “Enter Password,” enter the desired password and press <Enter>.

3. At the “Confirm Password” prompt, retype the desired password, then press <Enter>.
4. Select Save to CMOS and EXIT, type <Y>, then <Enter>.

To Change Password

1. Choose the Set Password option from the CMOS Setup Utility main menu and press <Enter>.
2. When you see “Enter Password,” enter the existing password and press <Enter>.
3. You will see “Confirm Password.” Type it again, and press <Enter>.
4. Select Set Password again, and at the “Enter Password” prompt, enter the new password and press <Enter>.
5. At the “Confirm Password” prompt, retype the new password, and press <Enter>.
6. Select Save to CMOS and EXIT, type <Y>, then <Enter>.

To Disable Password

1. Choose the Set Password option from the CMOS Setup Utility main menu and press <Enter>.
2. When you see “Enter Password,” enter the existing password and press <Enter>.
3. You will see “Confirm Password.” Type it again, and press <Enter>.
4. Select Set Password again, and at the “Enter Password” prompt, don’t enter anything; just press <Enter>.
5. At the “Confirm Password” prompt, again don’t type in anything; just press <Enter>.
6. Select Save to CMOS and EXIT, type <Y>, then <Enter>.

4.2.12 Save & Exit Setup

If you select this option and press <Y> then <Enter>, the values entered in the setup utilities will be recorded in the chipset’s CMOS memory. The microprocessor will check this every time you turn your system on and use the settings to configure the system. This record is required for the system to operate.

4.2.13 Exit Without Saving

Selecting this option and pressing <Enter> lets you exit the Setup program without recording any new values or changing old ones.

CHAPTER
5

PCI SVGA Setup

- Introduction
- Installation of SVGA drivers
 - for Windows 95/98/Me
 - for Windows NT/2000/XP
- Further information

Chapter 5 PCI SVGA Setup

5.1 Introduction

The ROBO-625 has an onboard AGP flat panel/VGA interface. The specifications and features are described as follows:

5.1.1 Chipset

The ROBO-625 uses a VIA Twister 8606T chipset from VIA Technology Inc. for its AGP/SVGA controller. It supports many popular LCD, and LVDS LCD displays and conventional analog CRT monitors. The VIA8606T VGA BIOS supports color TFT and LCD flat panel displays. In addition, it also supports interlaced and non-interlaced analog monitors (color and monochrome VGA) in high-resolution modes while maintaining complete IBM VGA compatibility. Digital monitors (i.e. MDA, CGA, and EGA) are NOT supported. Multiple frequency (multisync) monitors are handled as if they were analog monitors.

5.1.2 Display memory

The Twister chip can support 8/16/32MB frame buffer shared with system memory; the VGA controller can drive CRT displays or color panel displays with resolutions up to 1280 x 1024 at 16 M colors.

5.1.3 Display types

CRT and panel displays can be used simultaneously. The ROBO-625 can be set in one of three configurations: on a CRT, on a flat panel display, or on both simultaneously. The system is initially set to simultaneous display mode. If you want to enable the CRT display only or the flat panel display only, please contact VIA Technology Inc., or our sales representative for detailed information.

5.1.4 Dual/Simultaneous Display

The ROBO-625 uses a VIA Twister VT8606T LCD controller that is capable of providing simultaneous dual view display of the same content on a flat panel and CRT.

To set up dual view (simultaneous mode) under Windows 9x, Windows ME, Windows NT/2000/XP, follow these steps:

Step 1. Open the Control panel, and select "Display", "Settings".

Step 2. Select "CRT+LCD" or "CRT+TV" for dual view

Step 3. Click "OK".

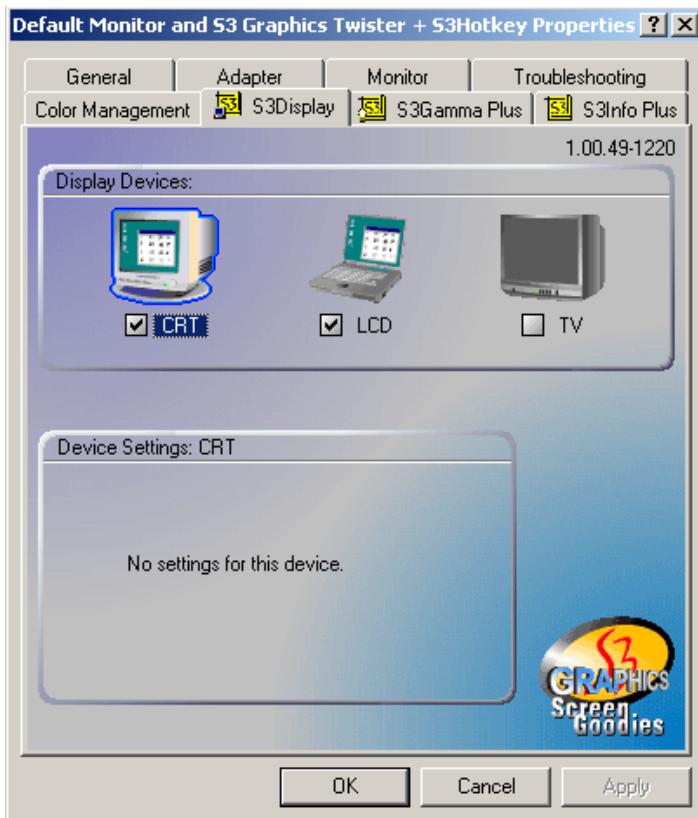


Figure 5.1: Selecting Display Settings

5.2 Installation of the SVGA Driver

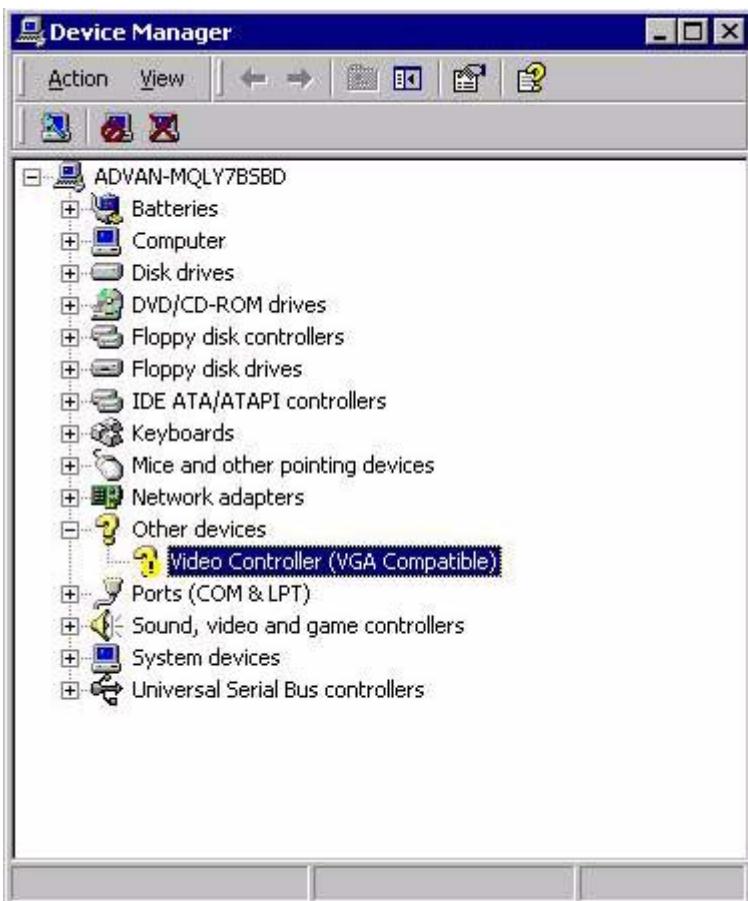
Complete the following steps to install the SVGA driver. Follow the procedures in the flow chart that apply to the operating system that you are using within your ROBO-625.

Notes:

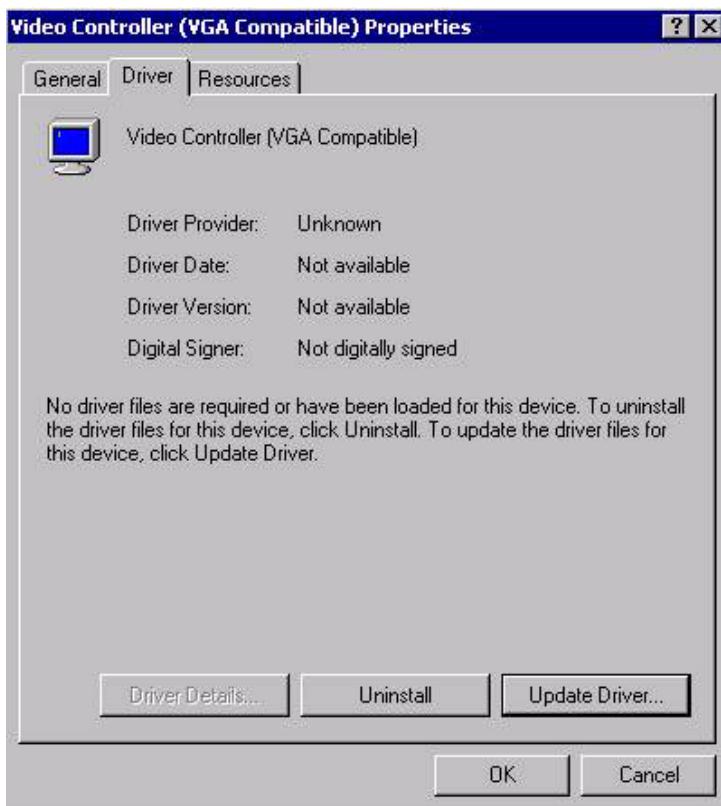
- 1. The windows illustrations in this chapter are intended as examples only. Please follow the listed steps, and pay attention to the instructions which appear on your screen.*
- 2. For convenience, the CD-ROM drive is designated as "E" throughout this chapter.*

5.2.1 Installation for Windows 2000

Step 1. Select “Start” > “Settings” > “Control Panel” > “System” > “Hardware” > “Device Manager.” Right click “Video Controller (VGA Compatible),” and choose “Properties.”



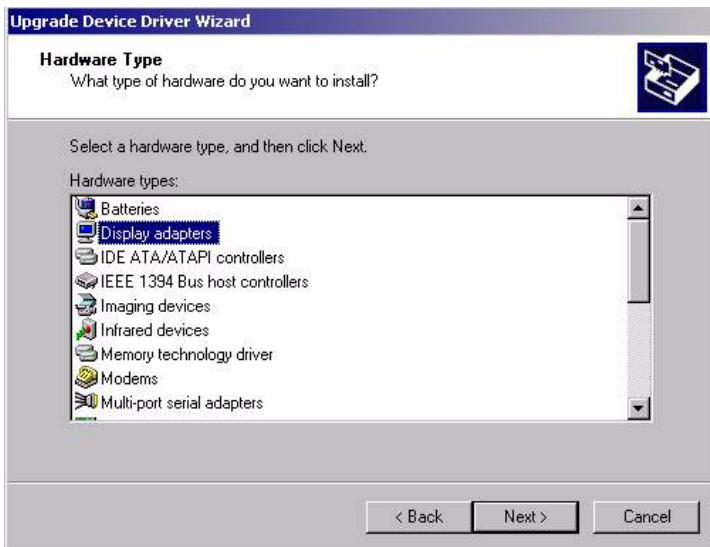
Step 2. Choose the “Driver” tab; press “Update Driver...” button.



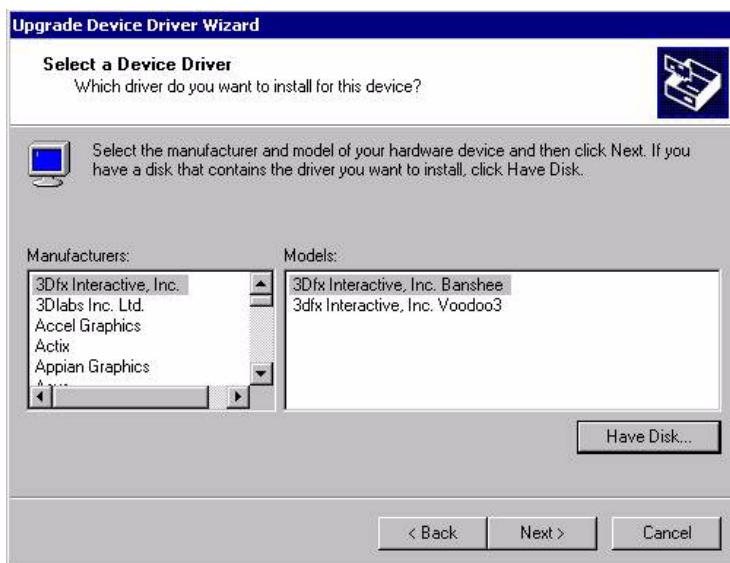
Step 3. Choose “Display a list of...,” then press “Next” button.



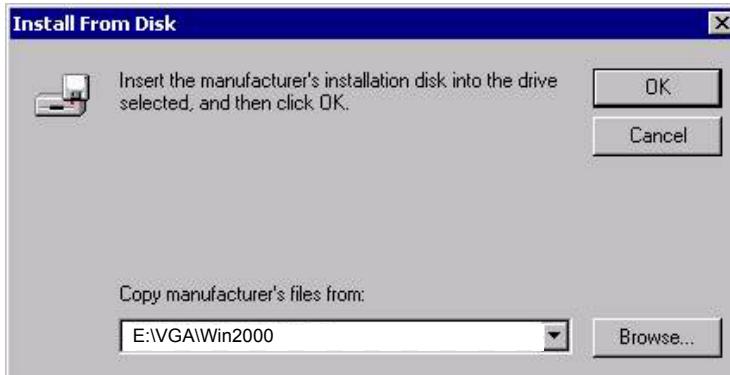
Step 4. Choose “Display adapters;” press “Next” button.



Step 5. Click the “Have Disk” button.



Step 6. Type the path to the Win2000 VGA drivers on your driver CD, and press the “OK” button.



Step 7. Press “Finish” to reboot.



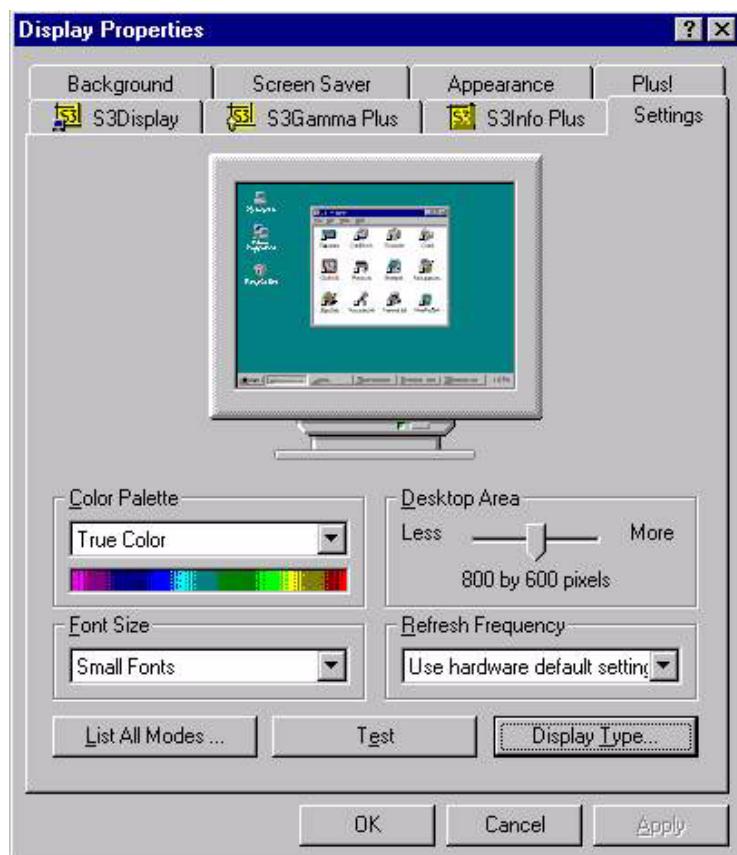
5.2.2 Installation for Windows NT

Note: Service Pack X (X = 3, 4, 5, 6,...) must be installed first, before you install the Windows NT VGA driver.

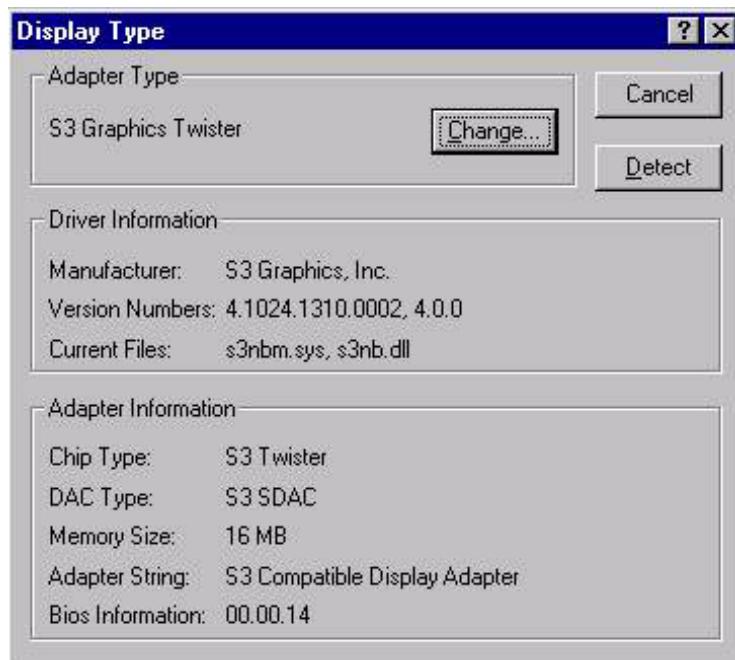
- Step 1. Select "Start", "Settings", "Control Panel" and double click the "Display" icon.



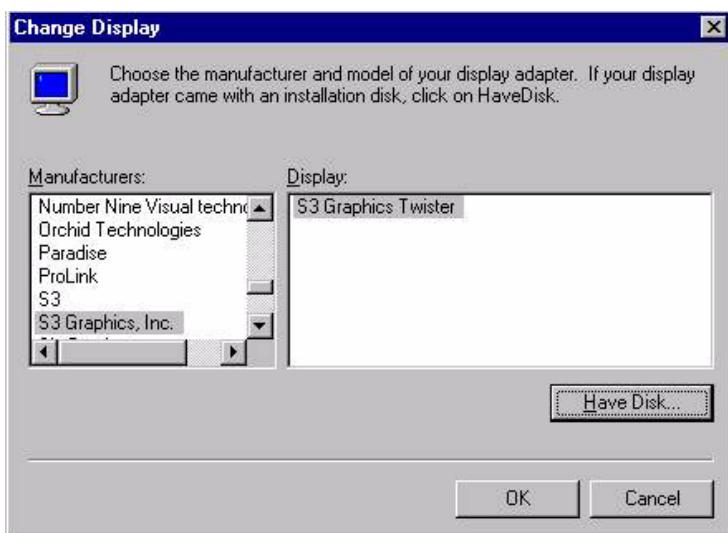
Step 2. Choose the "Settings" tab, and press the "Display Type" button.



Step 3. Press the "Change..." button.



Step 4. Click the "Have Disk..." button.



Step 5. Type the path to the WinNT VGA drivers on your installation CD, and press the "OK" button.

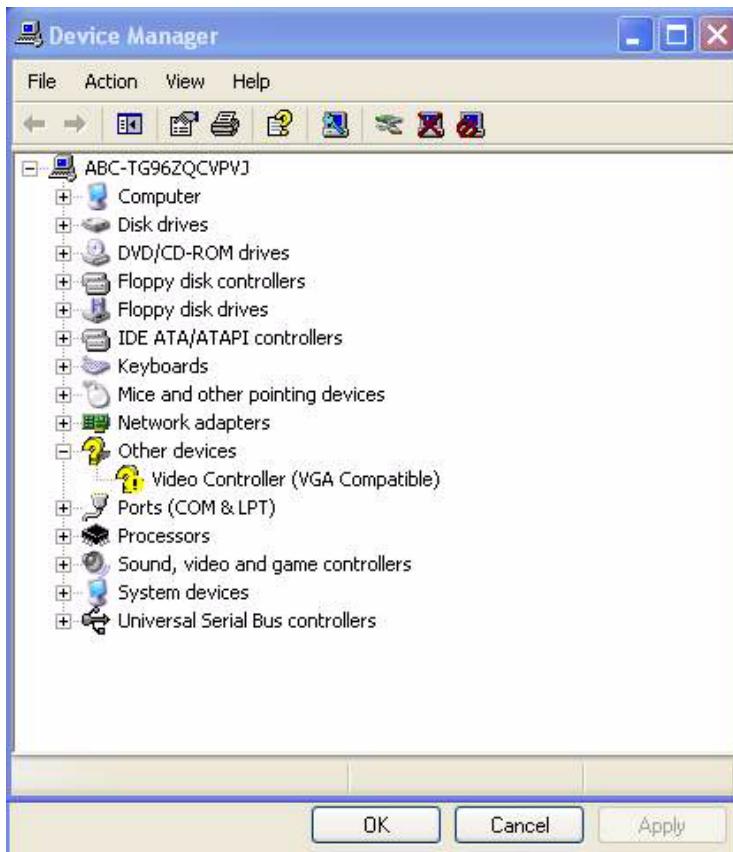


Step 6. Press “Finish” to complete the driver installation.



5.2.3 Installation for Windows XP

- Step 1. Select “Start,” “Settings,” “System,” “Control Panel” and double click the “system” icon. Choose “Hardware” and “Device Manager;” press “OK” button. Right click “Video Controller (VGA Compatible,” and select “Properties.”



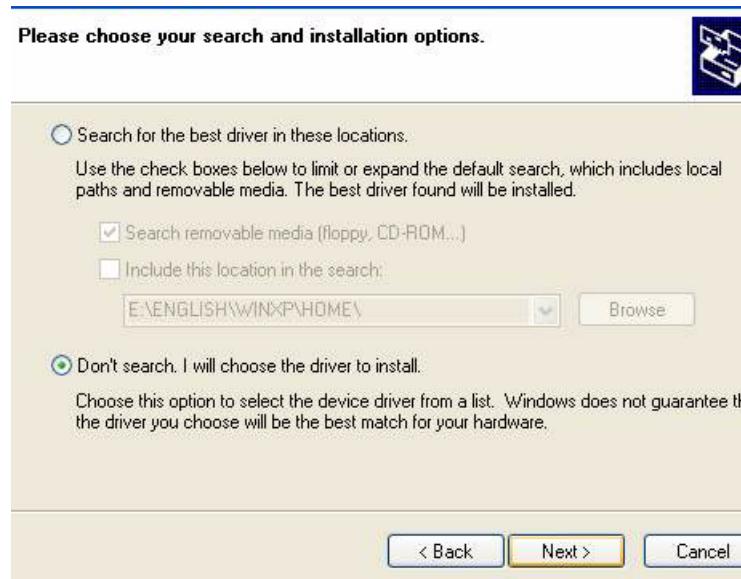
Step 2. Click “Update Driver.”



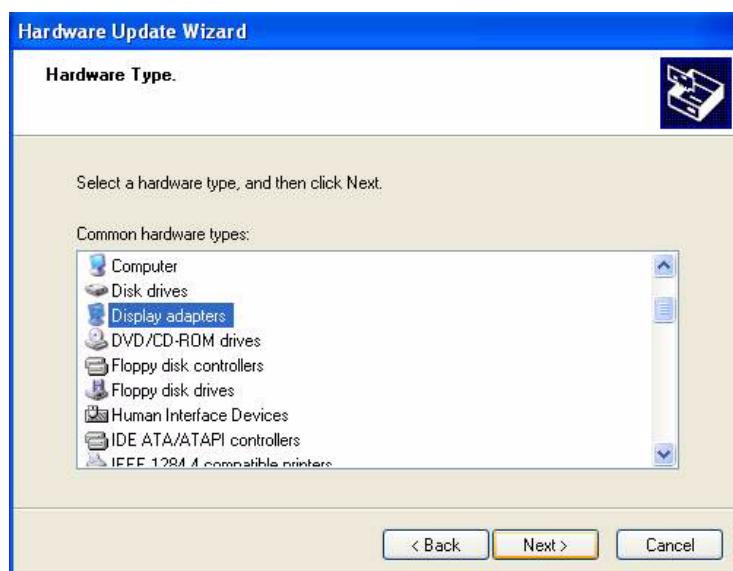
Step 3. The Hardware Update Wizard should start. Click the “Install from a list....” radio button; mash “Next.”



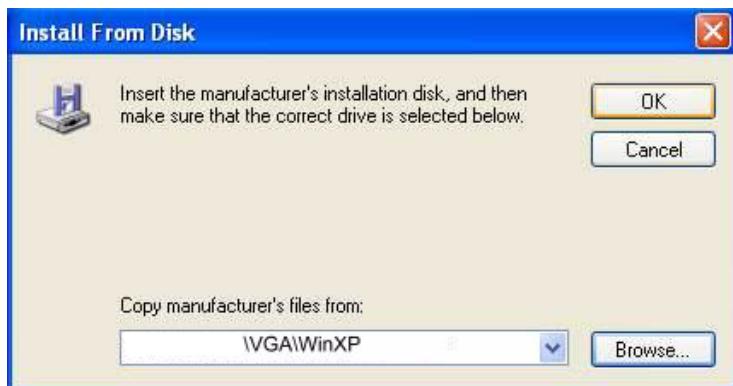
Step 4. Select “Don’t search. I will choose....” Depress “Next.”



Step 5. Select “Display adapters,” then press “Next.”



Step 6. Establish the path to the XP VGA drivers, then press “OK.”



Step 7. Select “S3 Graphics Twister + S3 Hotkey,” and click “Next.”



Step 8. Press “Finish” to reboot.



5.3 Further Information

For further information about the AGP/VGA installation in your ROBO-625, including driver updates, troubleshooting guides and FAQ lists, visit the following web resources:

VIA website: www.via.com.tw

Portwell websites: www.portwell.com

CHAPTER
6

Audio Setup

The ROBO-625 is equipped with an audio interface that records and plays back CD-quality audio. This chapter provides instructions for installing the software drivers included on the audio driver diskettes.

Chapter 6 Audio Setup

6.1 Introduction

The ROBO-625's on-board audio interface provides high-quality stereo sound and FM music synthesis (ESFM) by using the VIA VT82C686 audio controller from VIA. The audio interface can record, compress, and play back voice, sound, and music with built-in mixer control.

The ROBO-625 on board audio interface also supports the Plug and Play (PnP) standard and provides PnP configuration for the audio, FM, and MPU-104 logical devices. It is compatible with Sound BlasterTM; Sound Blaster ProTM version 3.01, voice and music functions. The ESFM synthesizer is register compatible with the OPL3 and has extended capabilities.

6.2 DOS utilities

6.2.1 VIA Sound Blaster Pro compatible set up program

Please “Enable” the Sound Blaster setting in the BIOS before playing Sound Blaster compatible DOS games. To enable the settings in the BIOS:

INTEGRATED PERIPHERALS -> Onboard Legacy Audio
 -> Sound Blaster (Disable -> Enable)

Chipset Feature Setup ->On Chip Sound (Disable-> Enable)

The Sound Blaster Pro compatible sound chip is integrated into the VIA PCI audio device in order to have Sound Blaster compatible DOS games running on the system.

If you want to play Sound Blaster compatible DOS games under the real mode MS-DOS or the “Restart in MS-DOS” from Win9x, then you should run this setup program to enable OPL3 MIDI music. Otherwise, the sound effects will be heard, but not the music. If you want to play legacy games in a Windows DOS Box, then you don't need to install this program.

6.2.2 VIA Sound Blaster Installation

Follow these steps to enable the Sound Blaster Pro compatible functions.

Step 1. Enable the Sound Blaster first on the BIOS setting of the "Onboard Legacy Audio" and "On-Chip Sound".

Step 2. Run the "Install.exe".

A:> INSTALL

Step 3. The program will copy the relative files into the directory which you assign. Next, the program will insert the following new line into the AUTOEXEC.BAT and copy the original AUTOEXEC.BAT to AUTOEXEC.VIA.

C:\VIAUDIO\VIAUDIO.COM

Step 4. Reboot the system when the installation is complete.

Step 5. Uninstall by deleting the new line from the AUTOEXEC.BAT.

6.3 Driver installation

6.3.1 Before you begin

Please read the instructions in this chapter carefully before you attempt installation. The audio drivers for the ROBO-625 board are located on the audio driver CD. Run the supplied SETUP program to install the drivers; don't copy the files manually.

Note: *The files on the software installation diskette are compressed. Do not attempt to install the drivers by copying the files manually. You must use the supplied SETUP program to install the drivers.*

6.3.2 Windows 95/98 drivers

- Step 1. Click "Start" and select "Settings". Click "Control Panel" and double-click "Add New Hardware".



- Step 2. In the Add New Hardware Wizard window, click "Next".



- Step 3. In the following Add New Hardware Wizard window, click "Next" for Windows to search for Plug and Play devices.



- Step 4. In the following Add New Hardware Wizard window, select “No, the device isn't in the list.” and click “Next”.



Step 5. In the following Add New Hardware Wizard window, select "No, I want to select..." and click "Next".



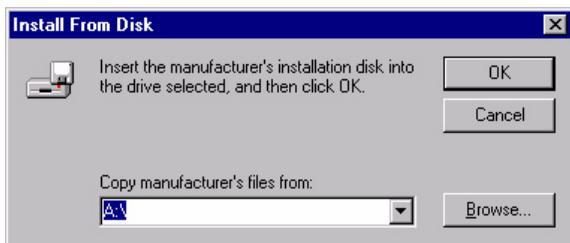
Step 6. In the following Add New Hardware Wizard window, select "Sound, video and game controllers" and click "Next".



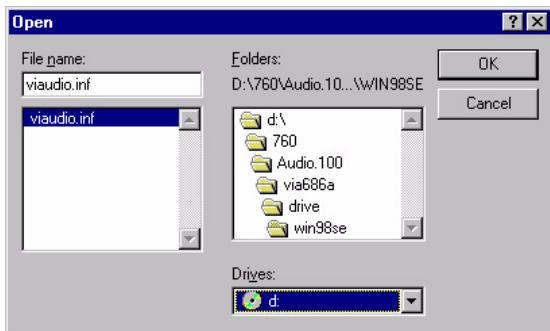
Step 7. In the following Add New Hardware Wizard window, click "Have Disk...".



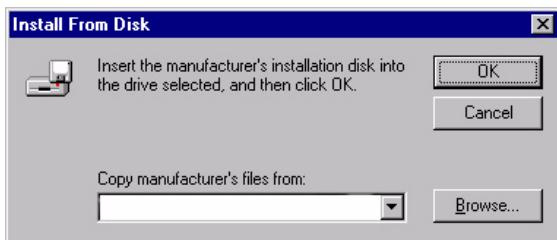
Step 8. In the Install From Disk window, click "Browse".



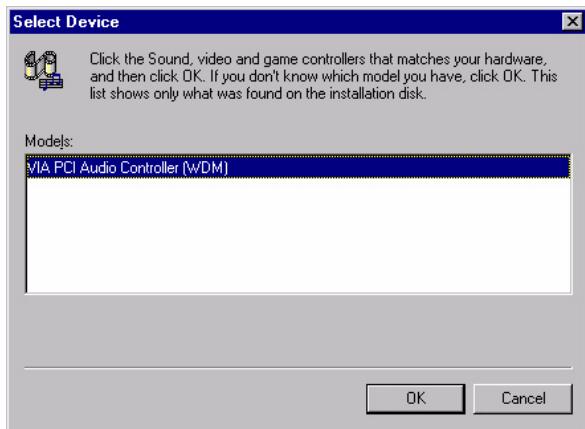
Step 9. In the Open window, select "E:\Audio\98se_Me_2k_xp\WIN95_98.



Step 10. In the Install From Disk window, click "OK".



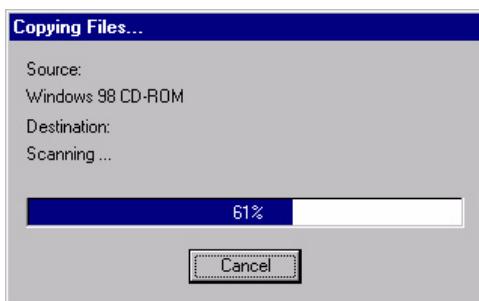
Step 11. In the Select Device window, select "VIA PCI Audio Controller (WDM)" and click "OK".



Step 12. In the Add New Hardware Wizard window, click "Next".



Step 13. The Copying Files... window will appear.

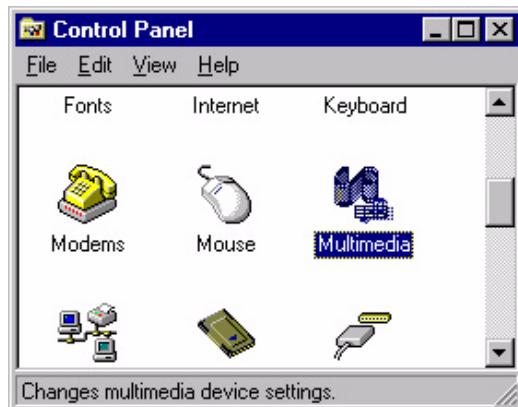


Step 14. In the Add New Hardware Wizard window, click "Finish". Then reboot the system.

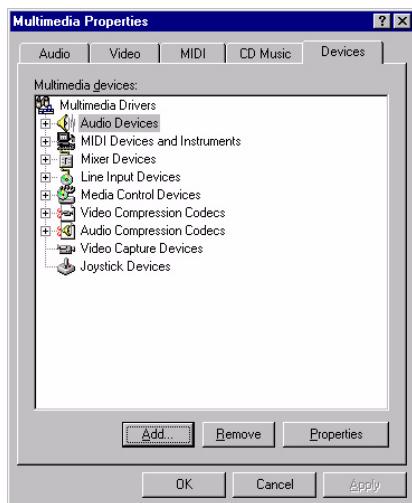


6.3.3 Windows NT drivers

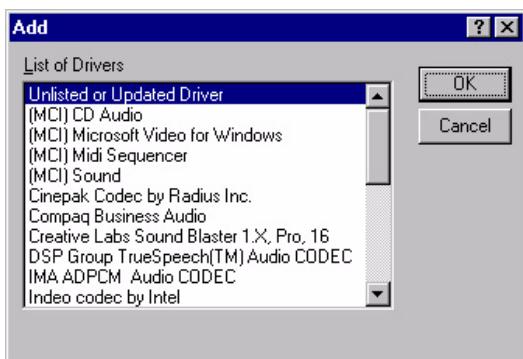
Step 1. Click "Start" and select "Settings". Click "Control Panel" and double-click "Multimedia".



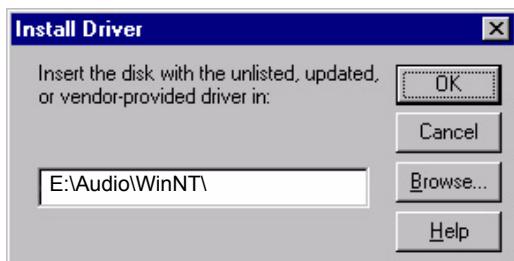
Step 2. In the Multimedia Properties window, select the "Devices" tab. Then select the "Audio Devices" item, and click "Add...".



Step 3. In the Add window, select the “Unlisted...” item and click “OK”.



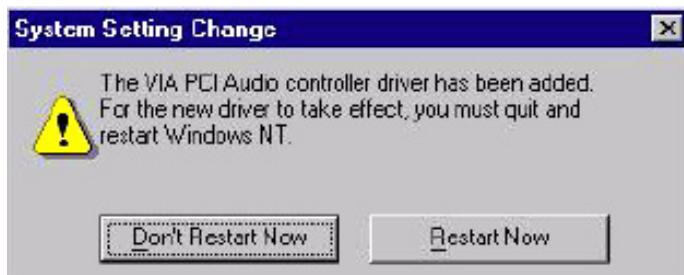
Step 4. When the Install Driver window appears, insert the utility disc into the CD-ROM drive. Type: E:\Audio\WinNT\
Then click “OK”.



Step 5. In the Add Unlisted or Updated Driver window, select the "VIA PCI Audio controller" item. Then click "OK".



Step 6. In the System Setting Change window, click "Restart Now".

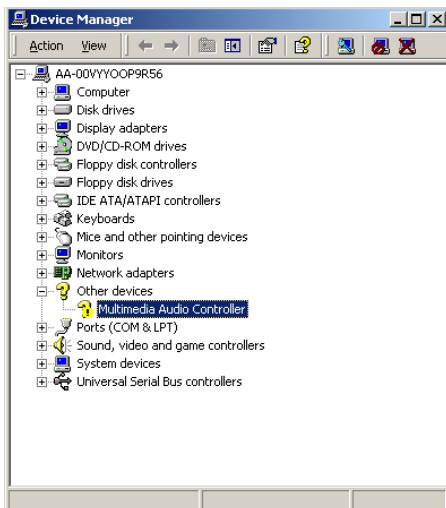


6.3.4 Windows 2000 Drivers

Step 1. Select “System”, “Setting”, “Control Panel” and double click “system” icon.



Step 2. Choose “Multimedia Audio Controller” button.



Step 3. Choose “Driver button, press “Update Driver” button.



Step 4. Choose “Sound, video and game controllers”, press “Next”



Step 5. Click the “Have Disk...” button



Step 6. Type the path E:\Audio\98se_Me_2k_xp\Win2000
press the “OK” button.



Step 7. Click “Have Disk” button



Step 8. Press “Next” button



Step 9. Press “Finish” to reboot



CHAPTER
7

PCI Bus Ethernet Interface

This chapter provides information on Ethernet configuration.

- Introduction
- Installation of Ethernet drivers for Windows 2000/NT
- Further information

Chapter 7 PCI Bus Ethernet Interface

7.1 Introduction

The ROBO-625 is equipped with a high performance 32-bit Ethernet chipset which is fully compliant with IEEE 802.3 100 Mbps CSMA/CD standards. It is supported by major network operating systems. It is also both 100Base-T and 10Base-T compatible. The medium type can be configured via the RSET8139.exe program included on the utility disk.

The Ethernet port provides one standard RJ-45 jacks via an optional wiring kit. The network boot feature can be utilized by incorporating the boot ROM image files for the appropriate network operating system. The boot ROM BIOS files are combined with system BIOS, which can be enabled/disabled in the BIOS setup.

7.2 Installation of Ethernet driver

Before installing the Ethernet driver, note the procedures below. You must know which operating system you are using in your ROBO-625 Series, and then refer to the corresponding installation flow chart. Then just follow the steps described in the flow chart. You will quickly and successfully complete the installation, even if you are not familiar with instructions for MS-DOS or Windows.

Note: *The windows illustrations in this chapter are examples only. Follow the steps and pay attention to the instructions which appear on your screen.*

7.2.1 Installation for MS-DOS and Windows 3.1

If you want to set up your Ethernet connection under the MS-DOS or Windows 3.1 environment, you should first check your server system model. For example, MS-NT, IBM-LAN server, and so on.

Then choose the correct driver to install in your SlotPC.

The installation procedures for various servers can be found on the supplied CD-ROM, the correct path being:

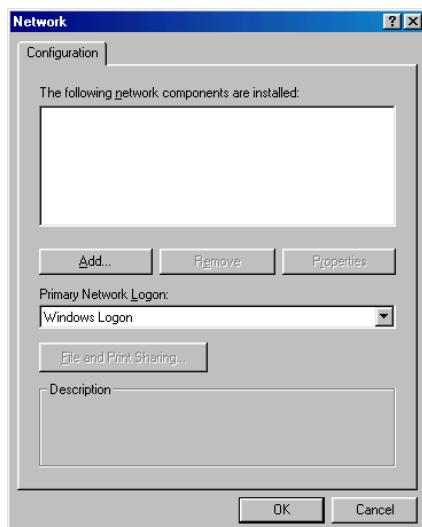
E:\LAN\8139C\wfw311

7.2.2 Installation for Windows 98

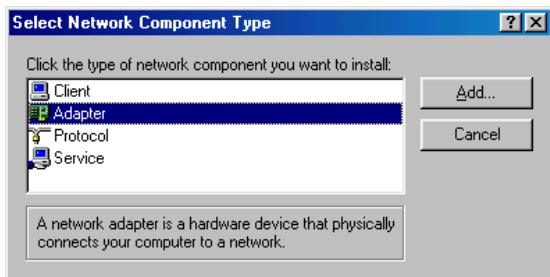
- Step 1. a. Select "Start", "Settings", "Control Panel".
b. Double click "Network".



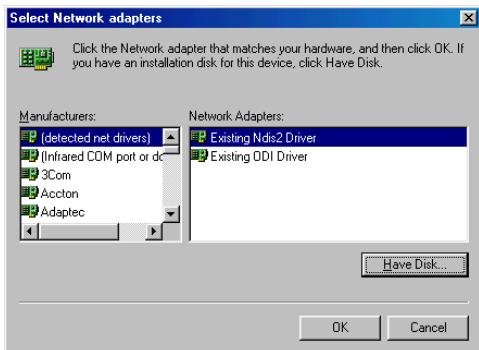
- Step 2. a. Click "Add" and prepare to install network functions.



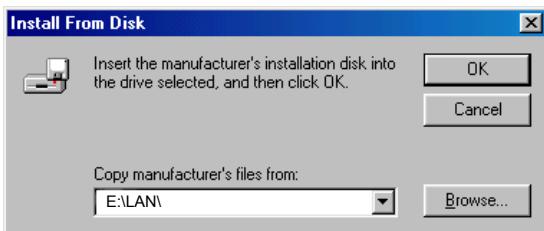
Step 3. a. Select the "Adapter" item to add the Ethernet card.



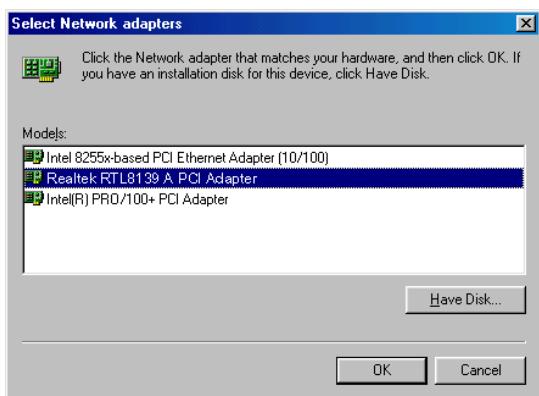
Step 4. a. Click "Have Disk" to install the driver.



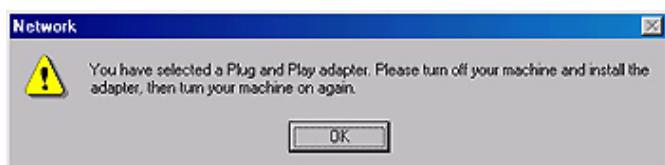
Step 5. a. Insert the CD into the D: drive
b. Fill in "E:\LAN"
c. Click "OK"



- Step 6. a. Choose the "Realtek RTL8139(A/B/C/8130) PCI Fast Ethernet" item.
b. Click "OK".

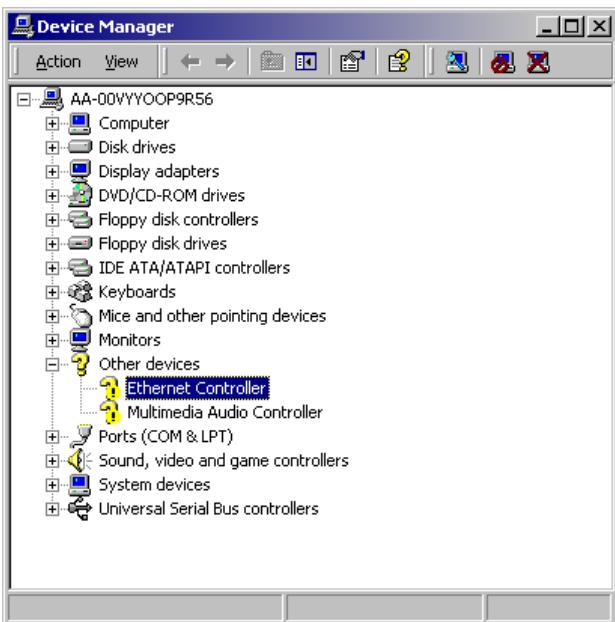


- Step 7. a. Make sure the configurations of relative items are set correctly.
b. Click "OK" to reboot.

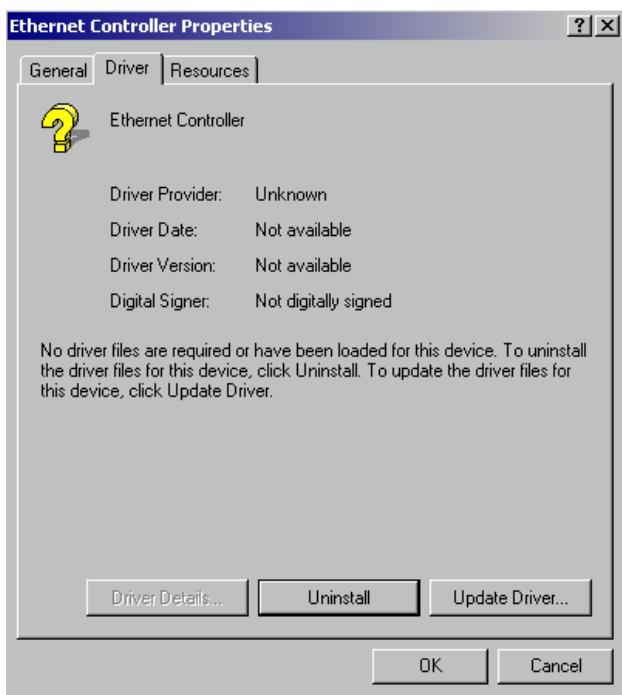


7.2.3 Installation for Windows 2000

Step 1. Open Device Manager,



Step 2.



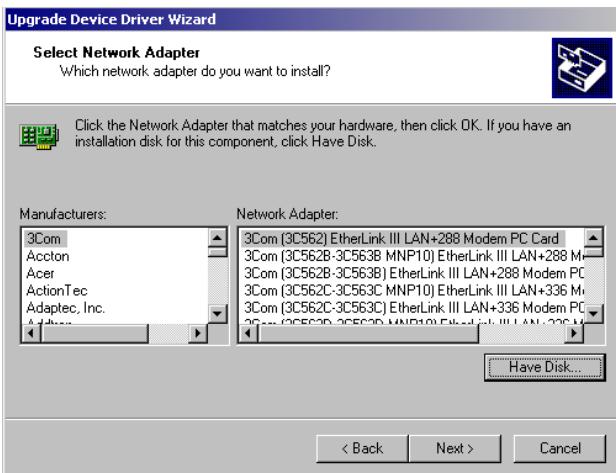
Step 3.



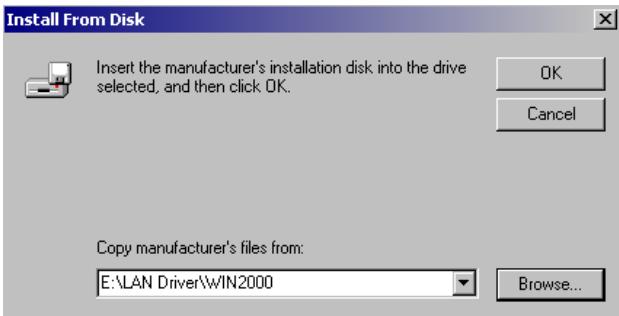
Step 4.



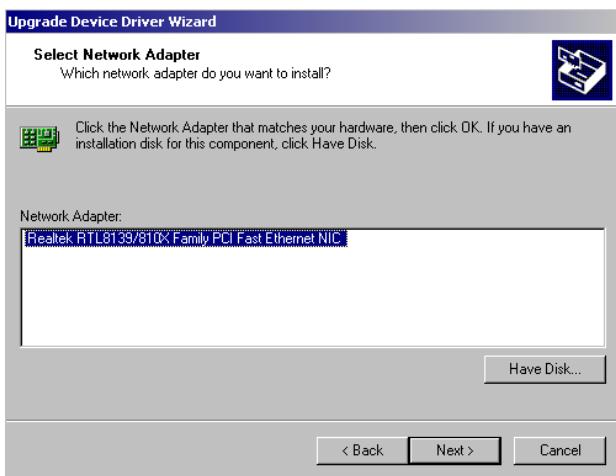
Step 5.



Step 6.



Step 7.



Step 8.

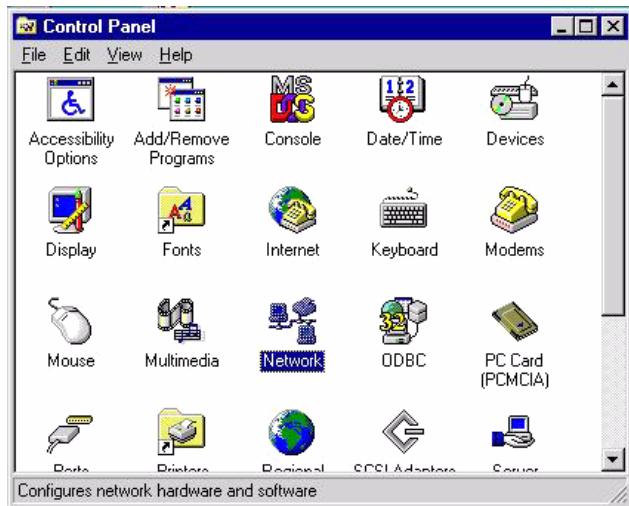


Step 9.



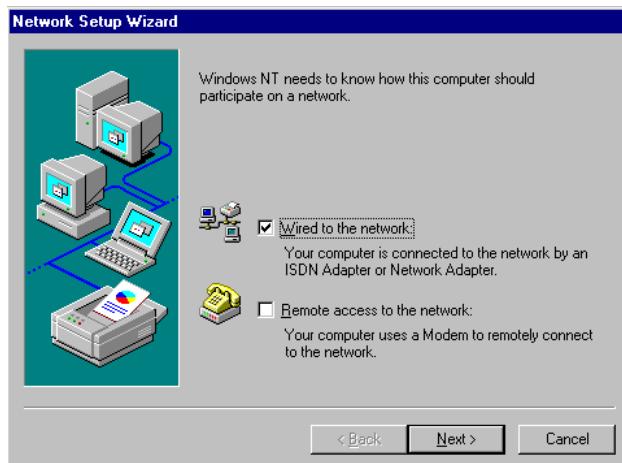
7.2.4 Installation for Windows NT

- Step 1. a. Select "Start", "Settings", "Control Panel"
b. Double click "Network"

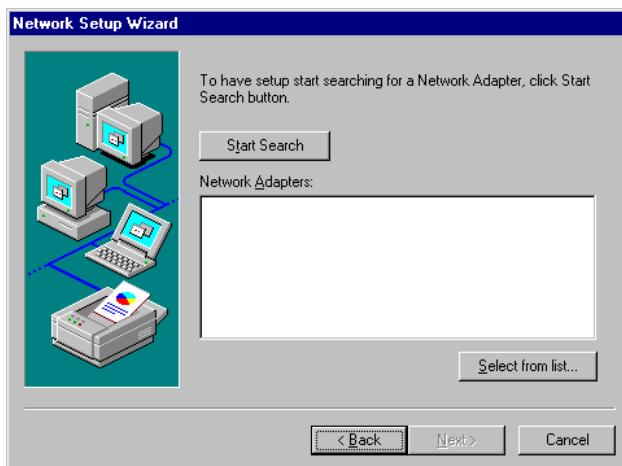


- Step 2. a. Choose type of network.

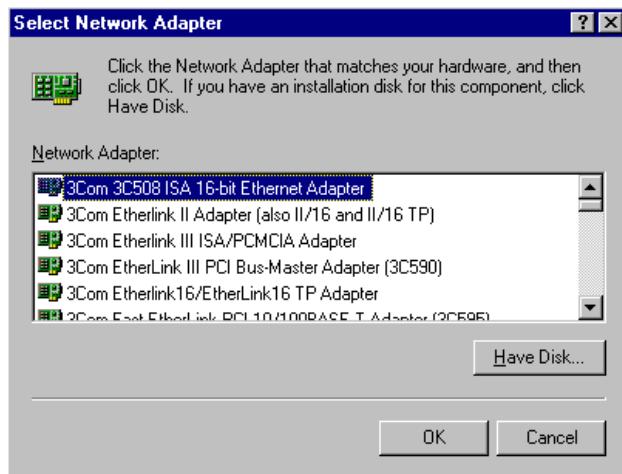
b. Click "Next"



Step 3. a. Click "Select from list..."



Step 4. Click "Have Disk."

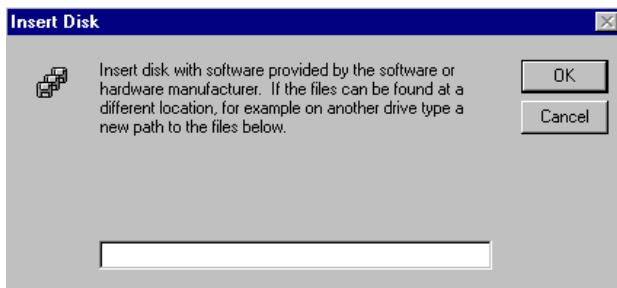


Step 5. a. Insert the Utility CD ROM

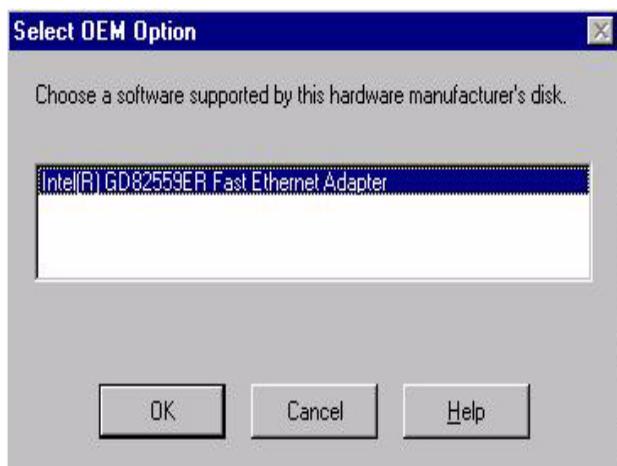
b. Fill in the correct path:

E:\LAN\8139C\winnt4

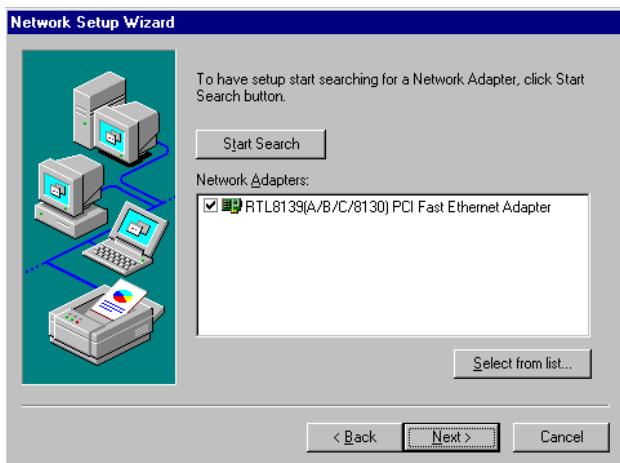
c. Click "OK".



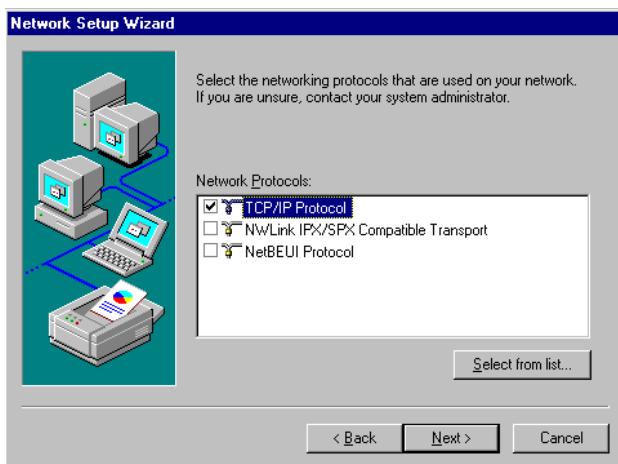
Step 6. Check the highlighted item, and click “OK.”



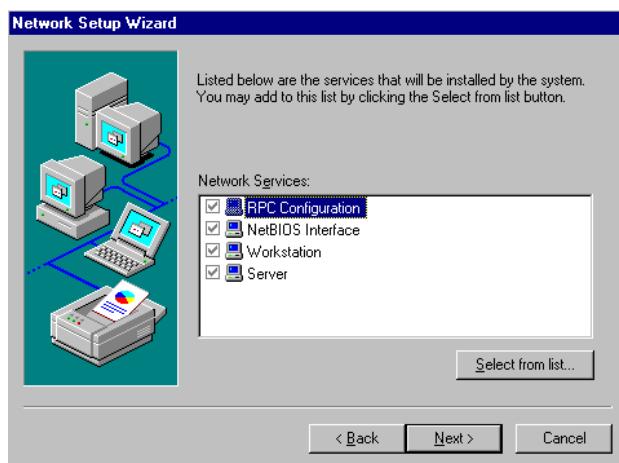
7. Click "Next" to continue setup.



- Step 8. Choose the networking protocols, then click "Next"



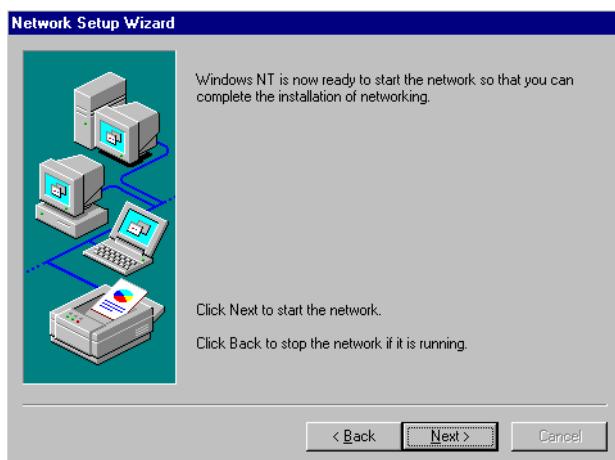
Step 9. Select the correct Network Services then click "Next"



Step 10. Click “Next” to continue setup.



11. Click “Next” to start the network.



7.3 Further information

Realtek website: www.realtek.com.tw
Intel website: www.intel.com
Portwell websites: www.portwell.com

Appendix

A

Programming the Watchdog Timer

The ROBO-625 is equipped with a watchdog timer that resets the CPU or generates an interrupt if processing comes to a standstill for any reason. This feature ensures system reliability in industrial standalone or unmanned environments.

Appendix A Programming the Watchdog Timer

A.1 Supported Input Timing Modes

In order to program the watchdog timer, you must write a program which writes I/O port address 443 (hex). The output data is a value of time interval. The value range is from 01 (hex) to 3E (hex), and the related time interval is 1 sec. to 62 sec.

| Data | Time Interval |
|------|---------------|
| 01 | 1 sec. |
| 02 | 2 sec. |
| 03 | 3 sec. |
| 04 | 4 sec. |
| . | . |
| . | . |
| 3E | 62 sec. |

After data entry, your program must refresh the watchdog timer by rewriting the I/O port 443 (hex) while simultaneously setting it. When you want to disable the watchdog timer, your program should read I/O port 443 (hex).

The following example shows how you might program the watchdog timer in BASIC:

```
10      REM Watchdog timer example program
20      OUT &H443, data  REM Start and restart the
                      watchdog
30      GOSUB 1000  REM Your application task #1
40      OUT &H443, data  REM Reset the timer
50      GOSUB 2000  REM Your application task #2
60      OUT &H443, data  REM Reset the timer
70      X=INP (&H443)  REM Disable the watchdog timer
80      END

1000    REM Subroutine #1, your application task
        .
        .
        .

1070    RETURN
2000    REM Subroutine #2, your application task
        .
        .
        .

2090    RETURN
```


Appendix

B

Filler

This filler appendix is supplied so that we can use the old Appendices C, D, and E, which are perfectly good, without changing all the references to them that appear in the text. Don't think for a moment that we *forgot* Appendix B. We didn't.

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Appendix C

Pin Assignments

This appendix contains information of a detailed or specialized nature. It includes:

- Suspend 5V and ATX PS_ON
- Parallel Port Connector
- Floppy Drive Connector
- Primary IDE Connector
- CRT Display Connector
- USB Connector
- LAN1, LAN2, LAN3, RJ45 connector
- Main Power Connector
- Power & HDD LED
- Flat Panel Connector
- LCD Inverter Backlight Connector
- Panel back-light VR connector
- Audio Connector
- Reset Button Connector
- Keyboard and PS/2 Mouse Connector
- CPU Fan Power Connector
- COM Port Connector
- ATX soft power switch Connector

Appendix C Pin Assignments

C.1 Suspend 5V and ATX PS_ON (CN1)



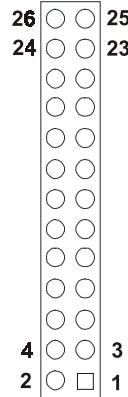
Table C.1: Suspend 5V and ATX PS_ON (CN1)

| Pin | Signal |
|-----|-------------------------|
| 1 | Suspend 5V input |
| 2 | GND |
| 3 | ATX PS_ON signal output |

C.2 Parallel Port Connector (CN2)

Table C.2: Parallel Port Connector (CN2)

| Pin | Signal | Pin | Signal |
|-----|--------|-----|--------|
| 1 | STB | 2 | AFD* |
| 3 | D0 | 4 | ERR |
| 5 | D1 | 6 | INIT* |
| 7 | D2 | 8 | SLIN* |
| 9 | D3 | 10 | GND |
| 11 | D4 | 12 | GND |
| 13 | D5 | 14 | GND |
| 15 | D6 | 16 | GND |
| 17 | D7 | 18 | GND |
| 19 | ACK* | 20 | GND |
| 21 | BUSY | 22 | GND |
| 23 | PE | 24 | GND |
| 25 | SLCT | 26 | NC |

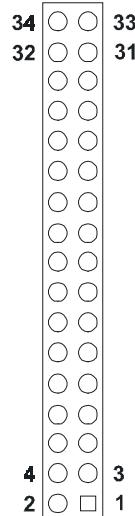


* low active

C.3 Floppy Disk Drive Connector (CN3)

Table C.3: Floppy Disk Drive Connector (CN3)

| Pin | Signal | Pin | Signal |
|-----|--------|-----|--------|
| 1 | GND | 2 | RWC |
| 3 | GND | 4 | NC |
| 5 | GND | 6 | NC |
| 7 | GND | 8 | Index |
| 9 | GND | 10 | MOA |
| 11 | GND | 12 | DSB |
| 13 | GND | 14 | DSA |
| 14 | GND | 16 | MOB |
| 17 | GND | 18 | DIR |
| 19 | GND | 20 | STEP |
| 21 | GND | 22 | WD |
| 23 | GND | 24 | WE |
| 25 | GND | 26 | Track0 |
| 27 | GND | 28 | WP |
| 29 | GND | 30 | RDATA |
| 31 | GND | 32 | HEAD |
| 33 | GND | 34 | DSKCHG |

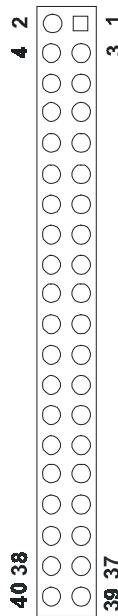


*low active

C.4 IDE Hard Drive Connector (CN4)

Table C.4: IDE HDD connector (CN4)

| Pin | Signal | Pin | Signal |
|-----|------------|-----|----------------------------|
| 1 | IDE RESET | 2 | GND |
| 3 | D7 | 4 | D8 |
| 5 | D6 | 6 | D9 |
| 7 | D5 | 8 | D10 |
| 9 | D4 | 10 | D11 |
| 11 | D3 | 12 | D12 |
| 13 | D2 | 14 | D13 |
| 15 | D1 | 16 | D14 |
| 17 | D0 | 18 | D15 |
| 19 | GND | 20 | NC |
| 21 | REQ | 22 | GND |
| 23 | IOW | 24 | GND |
| 25 | IOR | 26 | GND |
| 27 | READY | 28 | Cable Select (Pull-Low) |
| 29 | DACK | 30 | GND |
| 31 | IRQ14 | 32 | NC |
| 33 | A1 | 34 | Cable check |
| 35 | A0 | 36 | A2 |
| 37 | CS0 | 38 | CS1 |
| 39 | Active LED | 40 | GND |



C.5 CRT Display Connector (CN5)

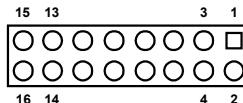


Table C.5: CRT Display Connector (CN5)

| Pin | Signal | Pin | Signal |
|-----|---------------------|-----|----------------------|
| 1 | Red signal output | 2 | +5V output |
| 3 | Green signal output | 4 | GND |
| 5 | Blue signal output | 6 | NC |
| 7 | NC | 8 | SPDAT singal I/O |
| 9 | GND | 10 | H-sync signal output |
| 11 | GND | 12 | V-sync signal output |
| 13 | GND | 14 | SPCLK signal I/O |
| 15 | GND | 16 | NC |

C.6 USB Connector (CN6)

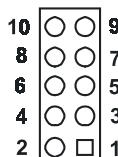


Table C.6: USB Connector (CN6)

| Pin | Signal | Pin | Signal |
|-----|---------|-----|---------|
| 1 | +5 V | 2 | +5 V |
| 3 | UV0- | 4 | UV1- |
| 5 | UV0+ | 6 | UV1+ |
| 7 | USB GND | 8 | USB GND |
| 9 | GND | 10 | N/C |

C.7 LAN1, LAN2, LAN3, RJ45 connector (CN7)

Table C.7: LAN1, LAN2, LAN3, RJ45 connector (CN7)

| Pin | Signal | Pin | Signal | Pin | Signal |
|--------|--------|--------|--------|--------|--------|
| LAN2-1 | TX+ | LAN3-1 | TX+ | LAN1-1 | TX+ |
| LAN2-2 | TX- | LAN3-2 | TX- | LAN1-2 | TX- |
| LAN2-3 | RX+ | LAN3-3 | RX+ | LAN1-3 | RX+ |
| LAN2-4 | N.C. | LAN3-4 | N.C. | LAN1-4 | N.C. |
| LAN2-5 | N.C. | LAN3-5 | N.C. | LAN1-5 | N.C. |
| LAN2-6 | RX- | LAN3-6 | RX- | LAN1-6 | RX- |
| LAN2-7 | N.C. | LAN3-7 | N.C. | LAN1-7 | N.C. |
| LAN2-8 | N.C. | LAN3-8 | N.C. | LAN1-8 | N.C. |

C.8 Main Power Connector (CN8)

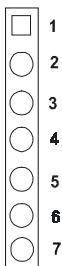


Table C.8: Main Power Connector (CN8)

| Pin | Signal |
|-----|------------|
| 1 | +5V input |
| 2 | GND |
| 3 | GND |
| 4 | +12V input |
| 5 | NC |
| 6 | GND |
| 7 | +5V input |

C.9 Power & HDD LED Connector(CN9)

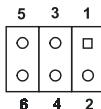


Table C.9: Power & HDD LED Connector (CN9)

| Pin | Signal |
|-----|-------------------|
| 1 | +5V output |
| 2 | GND |
| 3 | power LED+ (+5V) |
| 4 | HDD LED + |
| 5 | power LED - (GND) |
| 6 | HDD LED - |

C.10 Flat Panel Connector (CN12)

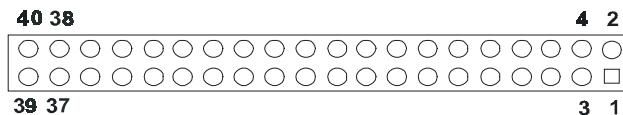


Table C.10: Flat Panel Connector (CN12)

| Pin | Signal | Pin | Signal |
|-----|---------------------|-----|--------------------|
| 1 | +5V output | 2 | +5V output |
| 3 | GND | 4 | GND |
| 5 | +3.3V output | 6 | +3.3V output |
| 7 | NC | 8 | GND |
| 9 | PD0 signal output | 10 | PD1 signal output |
| 11 | PD2 signal output | 12 | PD3 signal output |
| 13 | PD4 signal output | 14 | PD5 signal output |
| 15 | PD6 signal output | 16 | PD7 signal output |
| 17 | PD8 signal output | 18 | PD9 signal output |
| 19 | PD10 signal output | 20 | PD11 signal output |
| 21 | PD12 signal output | 22 | PD13 signal output |
| 23 | PD14 signal output | 24 | PD15 signal output |
| 25 | PD16 signal output | 26 | PD17 signal output |
| 27 | PD18 signal output | 28 | PD19 signal output |
| 29 | PD20 signal output | 30 | PD21 signal output |
| 31 | PD22 signal output | 32 | PD23 signal output |
| 33 | GND | 34 | GND |
| 35 | FPCLK signal output | 36 | FPVS signal output |
| 37 | FPDE signal output | 38 | FPHS signal output |
| 39 | NC | 40 | ENVEE signal |

Note:

The model number of the CN12 socket is DF13A-40DP-1.25V (Hirose Electric Co., Ltd.)

C.11 COM Connector (CN13, CN16)

Table C.11: COM connector (CN 13, CN16)

| COM1 connector (CN13) | | | | COM2 connector (CN16) | | | |
|-----------------------|--------|-----|--------|-----------------------|----------------|-----|--------|
| Pin | Signal | Pin | Signal | Pin | Signal | Pin | Signal |
| 1 | DCD | 6 | DSR | 1 | DCD/ 485TX- | 2 | DSR |
| 2 | RX | 7 | RTS | 3 | RX / 485TX+ | 4 | RTS |
| 3 | TX | 8 | CTS | 5 | TX / 485RX+ | 6 | CTS |
| 4 | DTR | 9 | RI | 7 | DTR/ 485RX- | 8 | RI |
| 5 | GND | | | 9 | GND | 10 | N.C. |

C.12 LCD Inverter Backlight Connector (CN14)

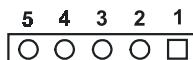


Table C.12: LCD Inverter Backlight Connector (CN14)

| Pin | Signal |
|-----|---------------------------------|
| 1 | +12V output |
| 2 | GND |
| 3 | Back-light enable signal output |
| 4 | Back-light VBR signal output |
| 5 | +5V output |

C.13 ATX soft power switch connector (CN15)

Table C.13: ATX soft power switch connector (CN15)

| Pin | Signal |
|-----|--------------------|
| 1 | PS_ON signal input |
| 2 | GND |

C.14 Panel back-light VR connector (CN17)

Table C.14: Panel back-light VR connector (CN17)

| Pin | Signal |
|-----|---------------------|
| 1 | Connect to VR Pin-1 |
| 2 | Connect to VR Pin-2 |
| 3 | Connect to VR Pin-3 |

C.15 Audio Connector (CN18)

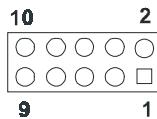


Table C.15: Audio connector (CN18)

| Pin | Signal | Pin | Signal |
|-----|------------|-----|--------|
| 1 | +5V Output | 2 | BITCLK |
| 3 | SDATIN | 4 | GND |
| 5 | GND | 6 | SYNC |
| 7 | SDATOUT | 8 | ACRST |
| 9 | +5V Output | 10 | N.C. |

C.16 Reset Button Connector (CN19)



Table C.16: Reset Button Connector (CN19)

| Pin | Signal |
|-----|--------------------|
| 1 | Reset signal input |
| 2 | GND |

C.17 Keyboard and PS/2 Mouse Connector (CN20)

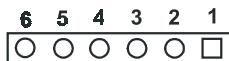


Table C.17: Keyboard and mouse connector (CN20)

| Pin | Signal |
|-----|----------|
| 1 | KB CLOCK |
| 2 | KB DATA |
| 3 | MS CLOCK |
| 4 | GND |
| 5 | +5V |
| 6 | MS DATA |

C.18 CPU Fan Power Connector (FAN 1)



Table C.18: IR connector (FAN 1)

| Pin | Signal |
|-----|-------------------------------|
| 1 | Fan speed detect signal input |
| 2 | +12V |
| 3 | GND |

Appendix D

System Assignments

This appendix contains information of a detailed nature. It includes:

- System I/O ports
- 1st MB memory map
- DMA channel assignments
- Interrupt assignments

Appendix D System Assignments

D.1 System I/O Ports

Table D.1: System I/O ports

| Addr. range (Hex) | Device |
|-------------------|--|
| 000-01F | DMA controller |
| 020-021 | Interrupt controller 1, master |
| 040-05F | 8254 timer |
| 060-06F | 8042 (keyboard controller) |
| 070-07F | Real-time clock, non-maskable interrupt (NMI) mask |
| 080-09F | DMA page register |
| 0A0-0BF | Interrupt controller 2 |
| 0C0-0DF | DMA controller |
| 0F0 | Clear math co-processor |
| 0F1 | Reset math co-processor |
| 0F8-0FF | Math co-processor |
| 1F0-1F8 | Fixed disk |
| 200-207 | Reserved (Game I/O) |
| 278-27F | Parallel printer port 2 (LPT 3) |
| 2E8-2EF | Series port 4 |
| 2F8-2FF | Serial port 2 |
| 300-31F | Prototype card |
| 360-36F | Reserved |
| 378-37F | Parallel printer port 1 (LPT 2) |
| 380-38F | SDLC, bisynchronous 2 |
| 3A0-3AF | Bisynchronous 1 |
| 3B0-3BF | Monochrome display and printer adapter (LPT1) |
| 3C0-3CF | Reserved |
| 3D0-3DF | Color/graphics monitor adapter |
| 3E8-3EF | Series port 3 |
| 3F0-3F7 | Diskette controller |
| 3F8-3FF | Serial port 1 |

* PNP audio I/O map range from 220 ~ 250H (16 bytes)
MPU-401 select from 300 ~ 330H (2 bytes)

D.2 1st MB memory map

Table D.2: 1st MB memory map

| Addr. range (Hex) | Device |
|-------------------|------------------------------------|
| F0000h - FFFFFh | System ROM |
| *CC000h - EFFFFh | Unused (reserved for Ethernet ROM) |
| C0000h - CBFFFh | Expansion ROM (for VGA BIOS) |
| B8000h - BFFFFh | CGA/EGA/VGA text |
| B0000h - B7FFFh | Unused |
| A0000h - AFFFFh | EGA/VGA graphics |
| 00000h - 9FFFFh | Base memory |

* If Ethernet boot ROM is disabled (Ethernet ROM occupies about 16 KB)

* E0000 - EFFFF is reserved for BIOS POST

D.3 DMA channel assignments

Table D.3: DMA channel assignments

| Channel | Function |
|---------|------------------------------|
| 0 | Available |
| 1 | Available (audio) |
| 2 | Floppy disk (8-bit transfer) |
| 3 | Available (parallel port) |
| 4 | Cascade for DMA controller 1 |
| 5 | Available |
| 6 | Available |
| 7 | Available |

* Audio DMA select 1, 3, or 5

** Parallel port DMA select 1 (LPT2) or 3 (LPT1)

D.4 Interrupt assignments

Table D.4: Interrupt assignments

| Interrupt# | Interrupt source |
|-------------------|---------------------------------------|
| IRQ 0 | Interval timer |
| IRQ 1 | Keyboard |
| IRQ 2 | Interrupt from controller 2 (cascade) |
| IRQ 3 | COM2 |
| IRQ 4 | COM1 |
| IRQ 5 | COM4 |
| IRQ 6 | FDD |
| IRQ 7 | LPT1 |
| IRQ 8 | RTC |
| IRQ 9 | Reserved (audio) |
| IRQ 10 | COM3 |
| IRQ 11 | Reserved for watchdog timer |
| IRQ 12 | PS/2 mouse |
| IRQ 13 | INT from co-processor |
| IRQ 14 | Primary IDE |
| IRQ 15 | Secondary IDE for CFC |

* Ethernet interface IRQ select: 9, 11, 15

* PNP audio IRQ select: 9, 11, 15

* PNP USB IRQ select: 9, 11, 15

* PNP ACPI IRQ select: 9, 11, 15

Optional Extras for the ROBO-625

E.1 ATX Power Control Cable

Please contact Portwell